

LOCAL COMPUTATION OF HOMOLOGY VARIATIONS RELATED TO CELLS MERGING

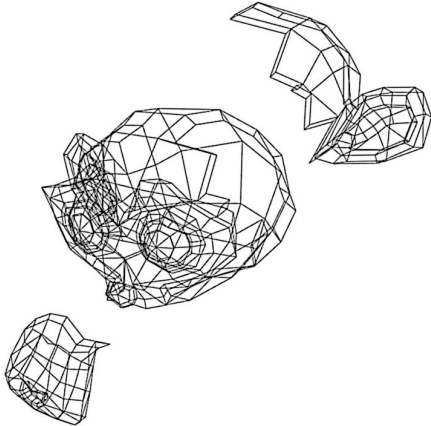
Theoretical results and implementation issues



1: CONTEXT AND OBJECTIVES

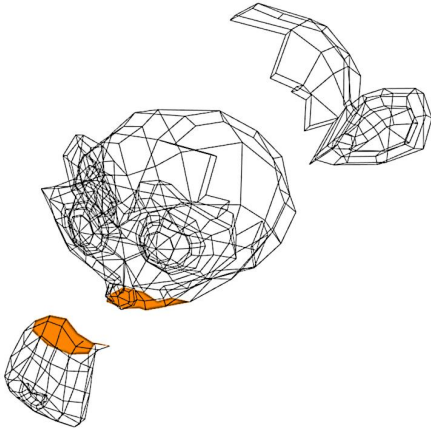
1

CONTEXT AND OBJECTIVES



1

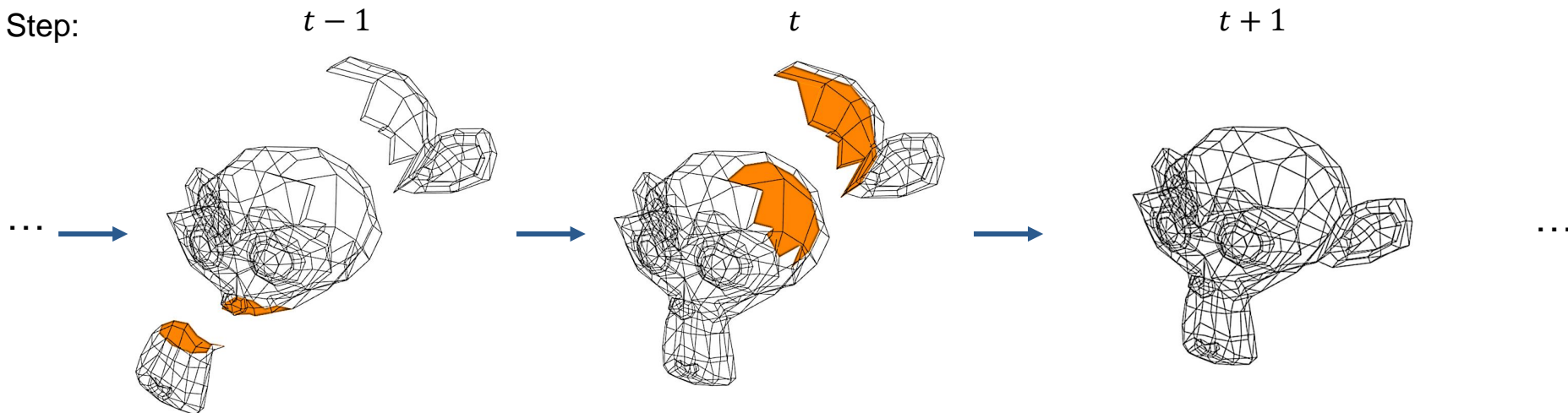
CONTEXT AND OBJECTIVES



1

CONTEXT AND OBJECTIVES

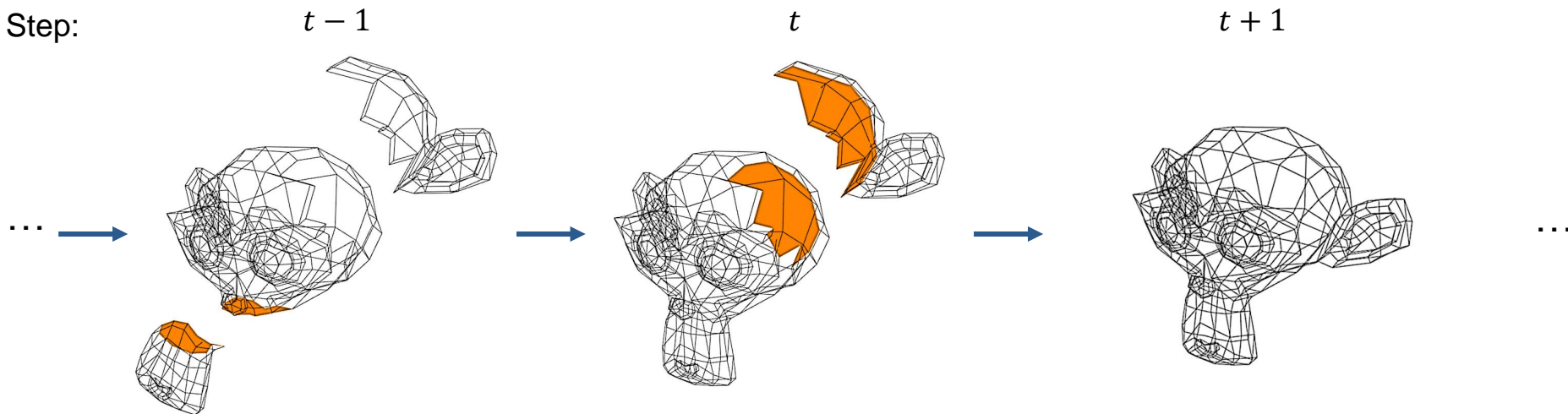
Step:



1

CONTEXT AND OBJECTIVES

Step:

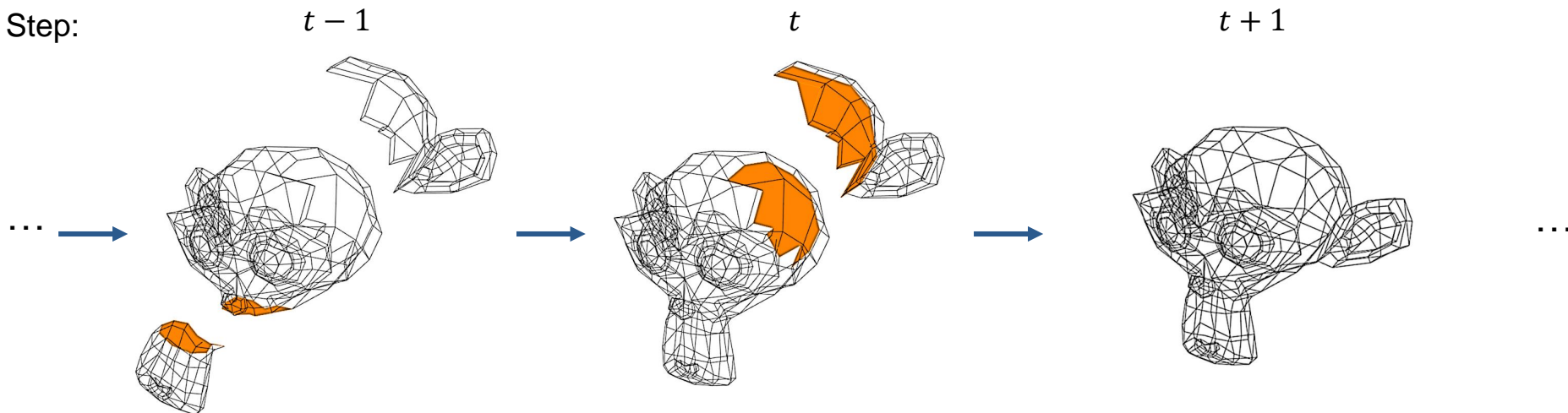


Operation: merging cells

1

CONTEXT AND OBJECTIVES

Step:



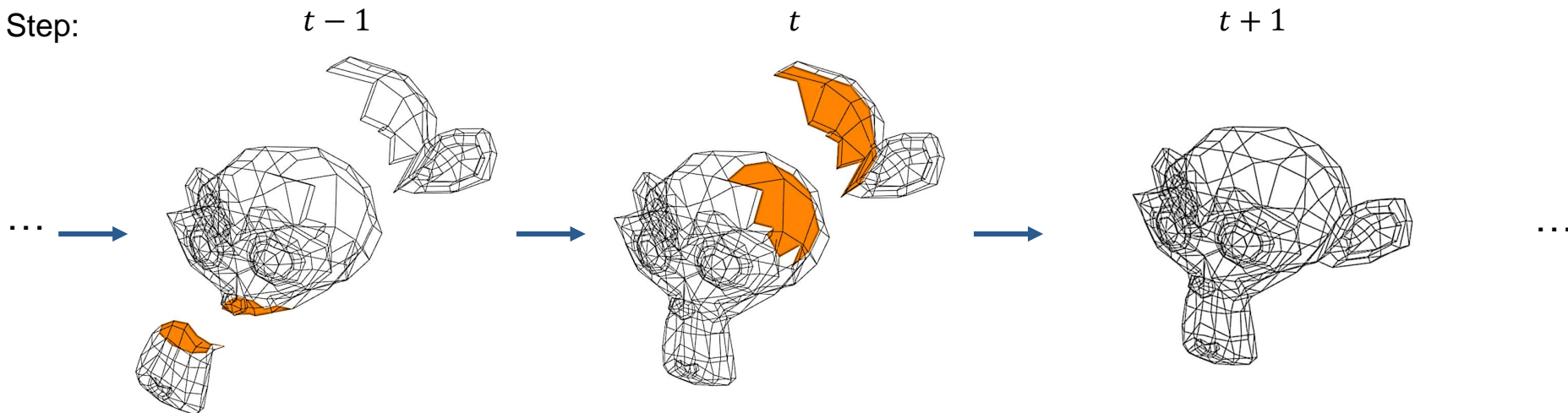
Operation: **merging cells**

At each step: control of the object construction according to computed information

1

CONTEXT AND OBJECTIVES

Step:



Operation: **merging cells**

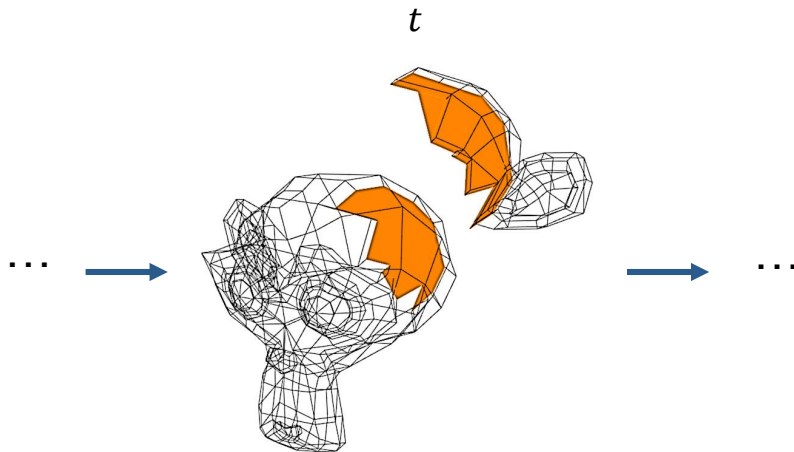
At each step: control of the object construction according to computed information

=> Compute homology efficiently

2: STATE OF THE ART

2

SMITH NORMAL FORM (SNF)



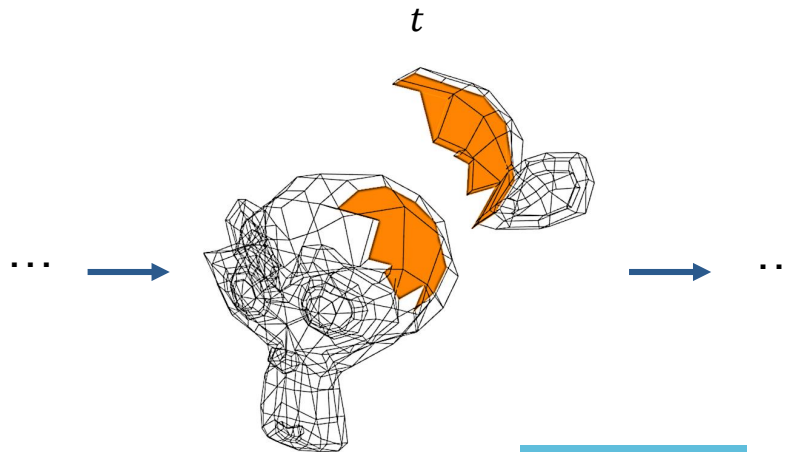
At each step:

Boundary
matrices

- Munkres, James R. (1984). *Elements of algebraic topology*.
- Hatcher, Allen. (2002). *Algebraic topology*.

2

SMITH NORMAL FORM (SNF)



At each step:

Boundary
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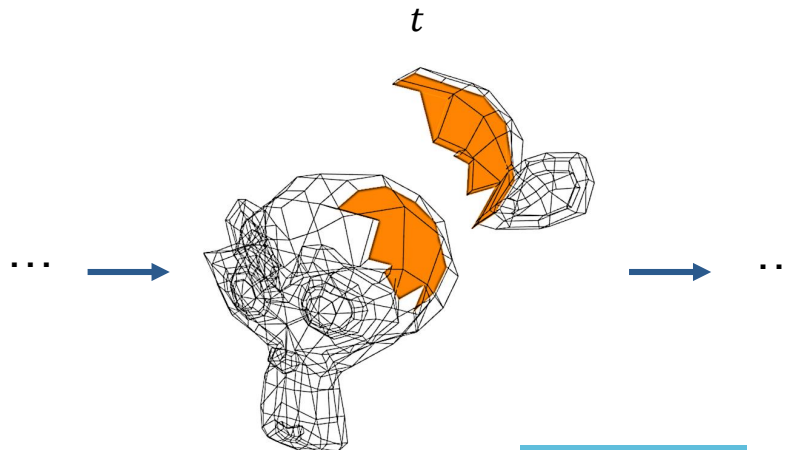
Smith Normal Form

SNF
Matrices

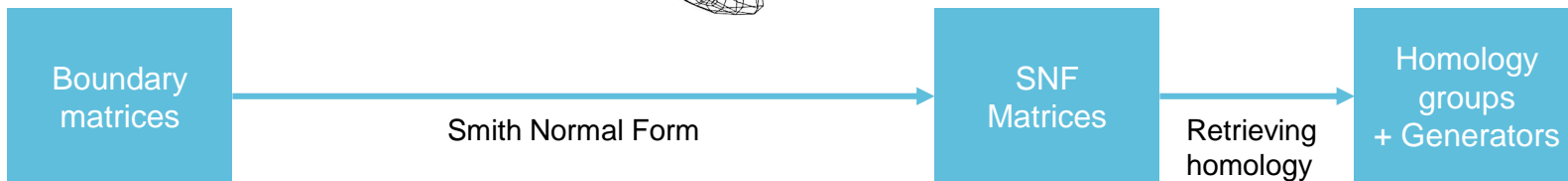
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2

SMITH NORMAL FORM (SNF)



At each step:

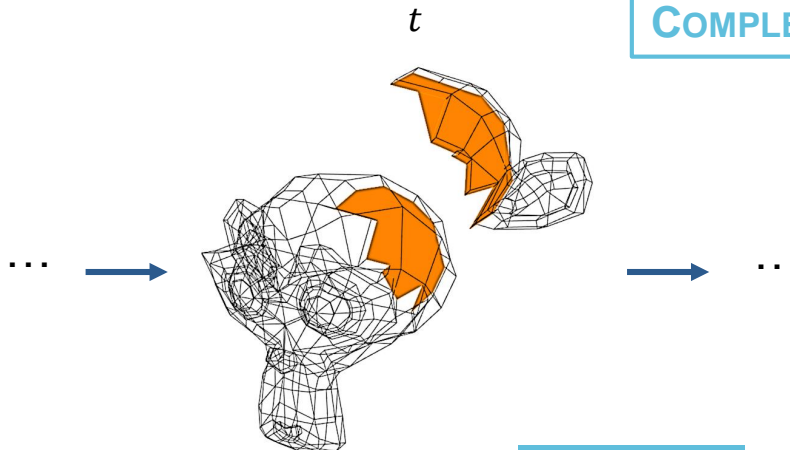


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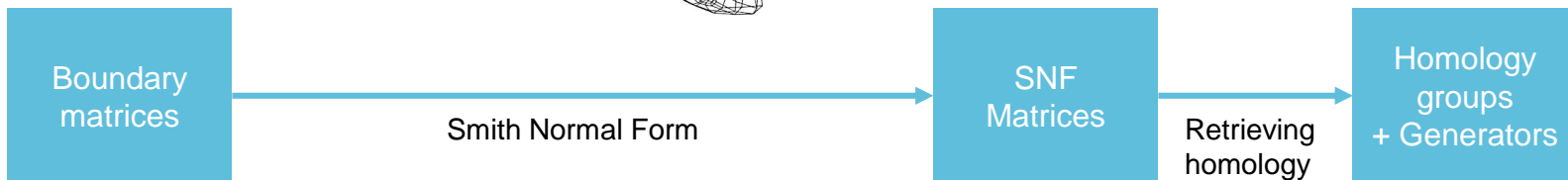
2

SMITH NORMAL FORM (SNF)

COMPLEXITY: SIZE OF THE OBJECT



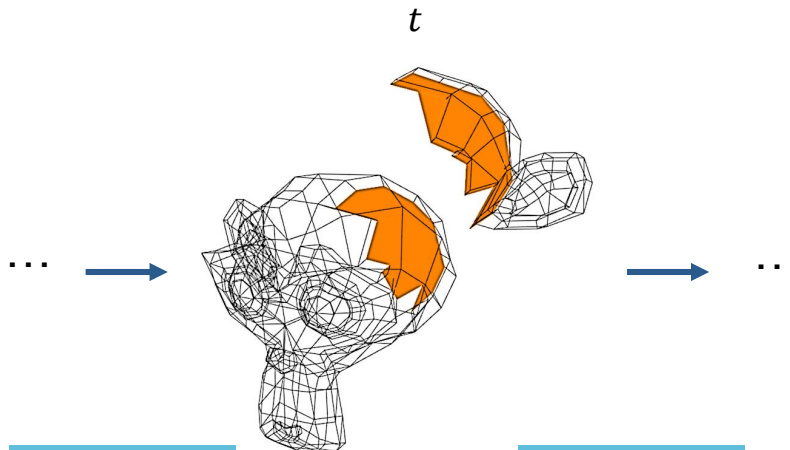
At each step:



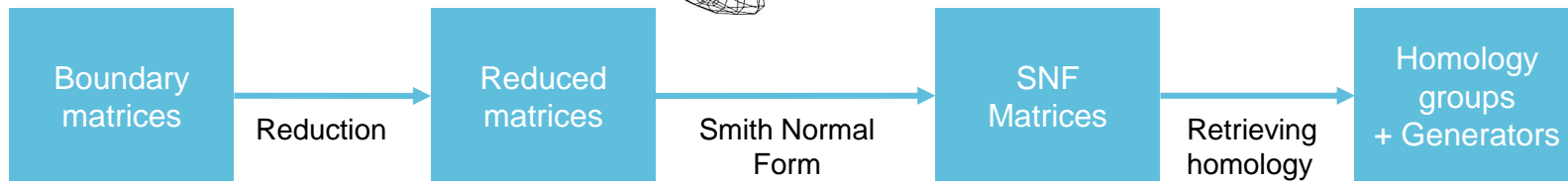
- Munkres, James R. (1984). *Elements of algebraic topology*.
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2

REDUCTION



At each step:

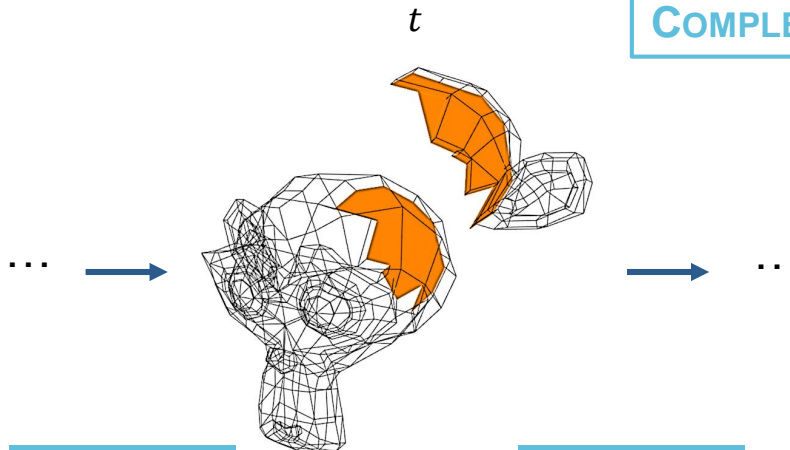


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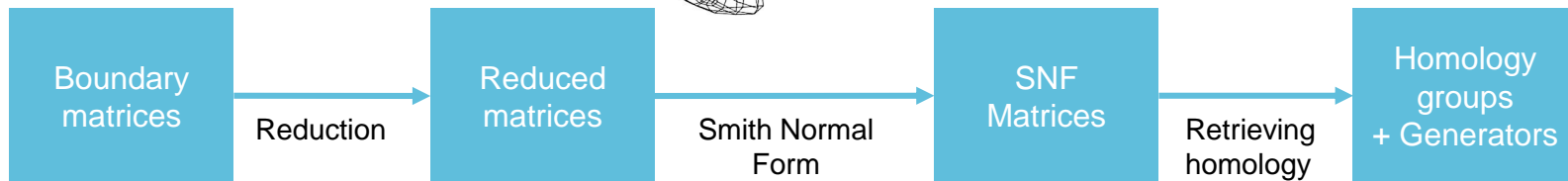
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REDUCTION

COMPLEXITY: SIZE OF THE OBJECT



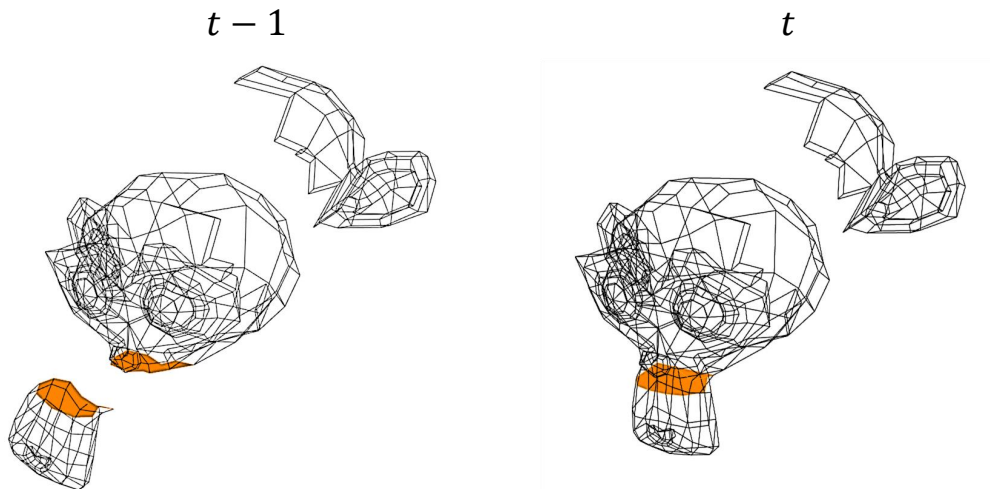
At each step:



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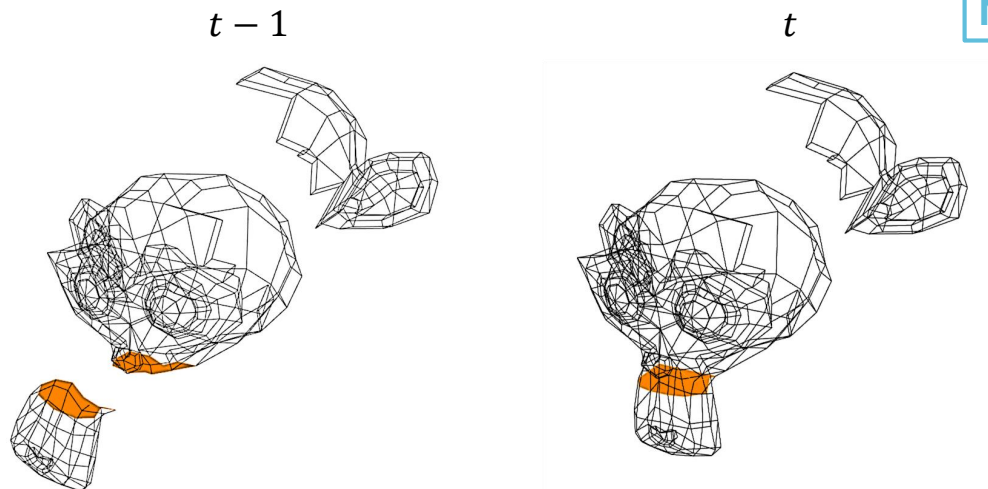
PERSISTENT HOMOLOGY



- Zomorodian, A., & Carlsson, G. (2005). *Computing persistent homology*.
- Edelsbrunner, H., Letscher, D., & Zomorodian, A. (2000). *Topological persistence and simplification*.

2

PERSISTENT HOMOLOGY

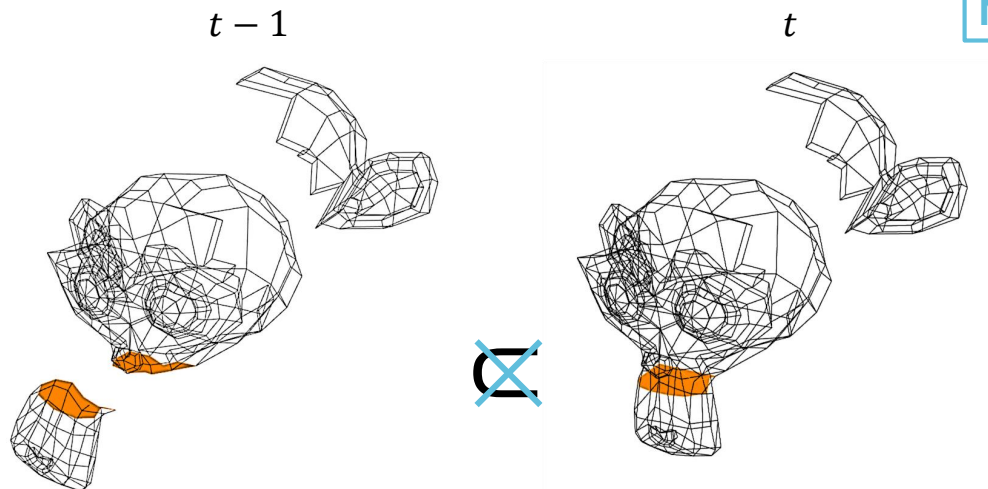


NO FILTRATION WHEN MERGING CELLS

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PERSISTENT HOMOLOGY



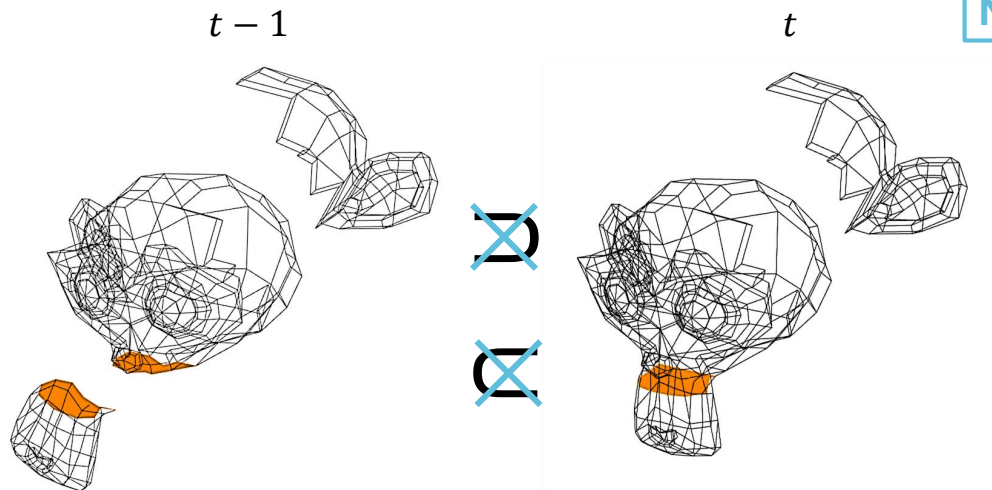
NO FILTRATION WHEN MERGING CELLS

- From $t - 1$ to t : merged cells

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2

PERSISTENT HOMOLOGY



- From $t - 1$ to t : merged cells
- From t to $t - 1$: modified boundary

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- Edelsbrunner, H., Letscher, D., & Zomorodian, A. (2000). *Topological persistence and simplification*.

2

SHORT EXACT SEQUENCE BASED METHOD

Goal

- Tracking homology variations induced by a merging operation
- Taking advantage of locality => complexity: size of the operated part

- D. Boltcheva, D. Canino, S. Merino Aceituno, J.-C. Leon, L. De Floriani, and F. Hetroy. An iterative algorithm for homology computation on simplicial shapes.
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Contributions

- Theoretical and experimental complexity in the case of the merging cells operation
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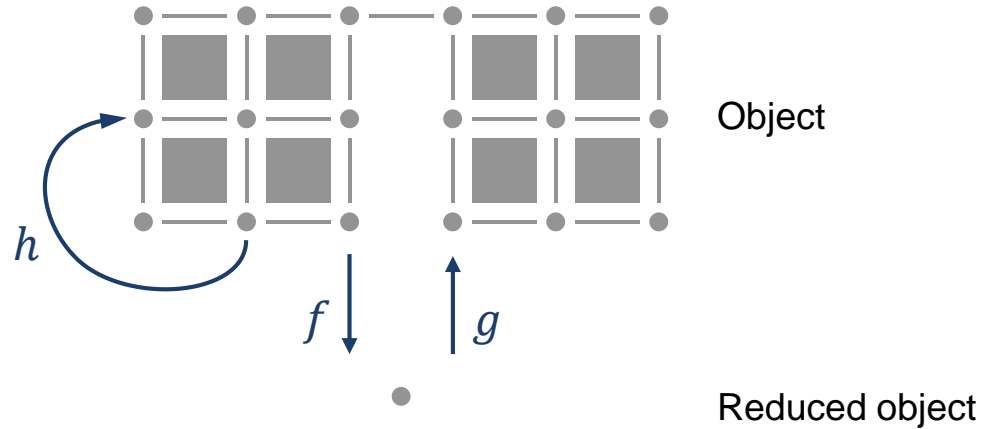
Contributions

- Theoretical and experimental complexity in the case of the merging cells operation
 - Highlighting critical cases
-
- D. Boltcheva, D. Canino, S. Merino Aceituno, J.-C. Leon, L. De Floriani, and F. Hetroy. An iterative algorithm for homology computation on simplicial shapes.
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3: TOOLS

3

REDUCTION

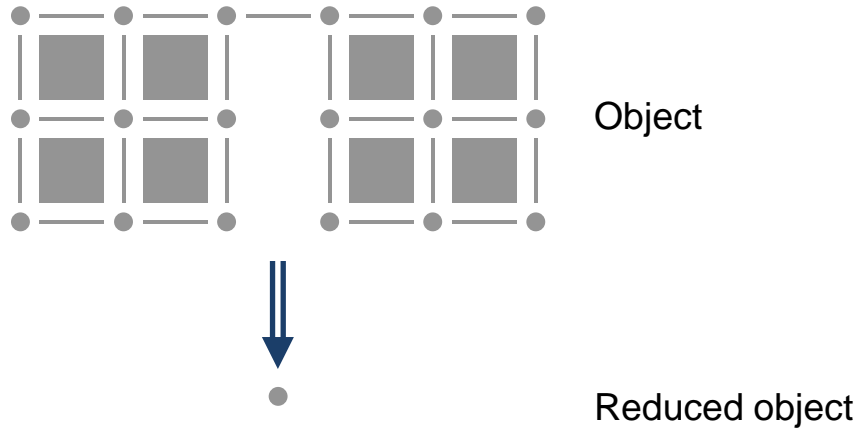


Reducing object while preserving homology

- 3 morphisms h, f, g

3

REDUCTION

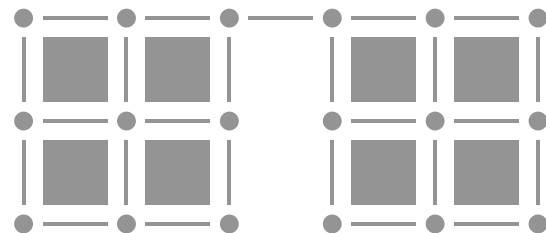
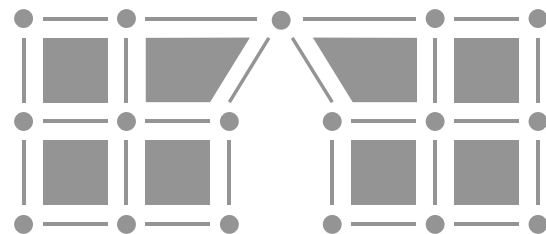


Reducing object while preserving homology

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3

HOMOLOGICAL EQUIVALENCE



3 objects with same homology

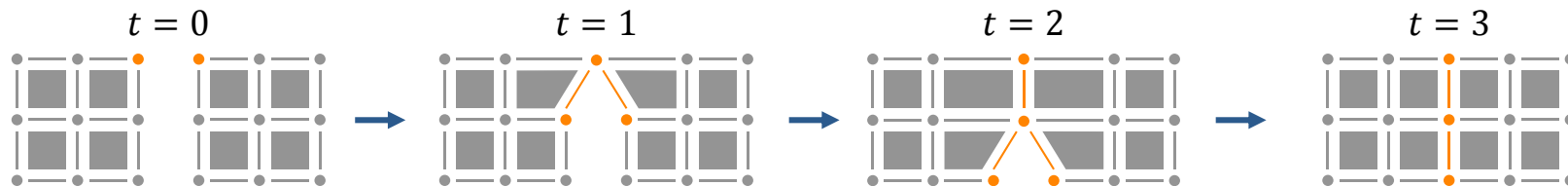
- 2 reductions

4: METHOD

4

METHOD: STUDIED OPERATION SET

3 operations, 4 construction steps

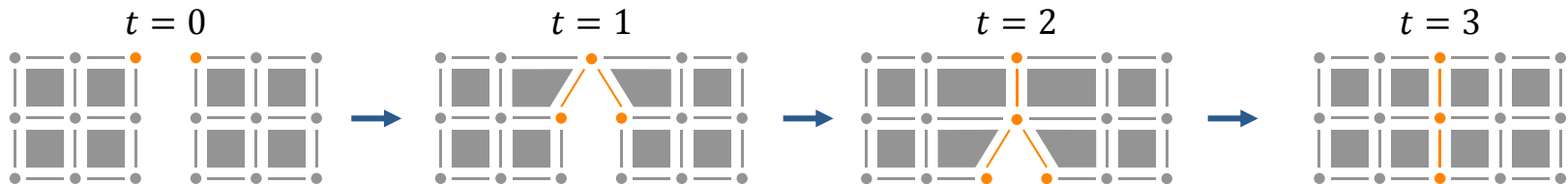


4

METHOD: PRINCIPLE

3 operations, 4 construction steps

Maintain a homological equivalence

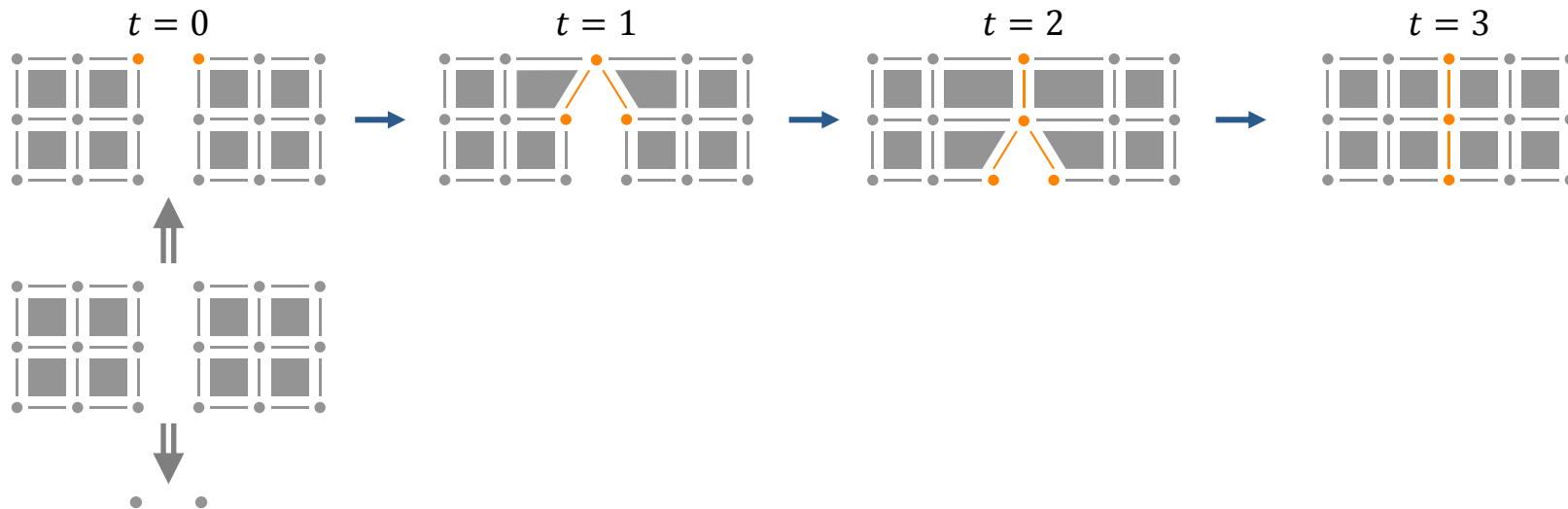


4

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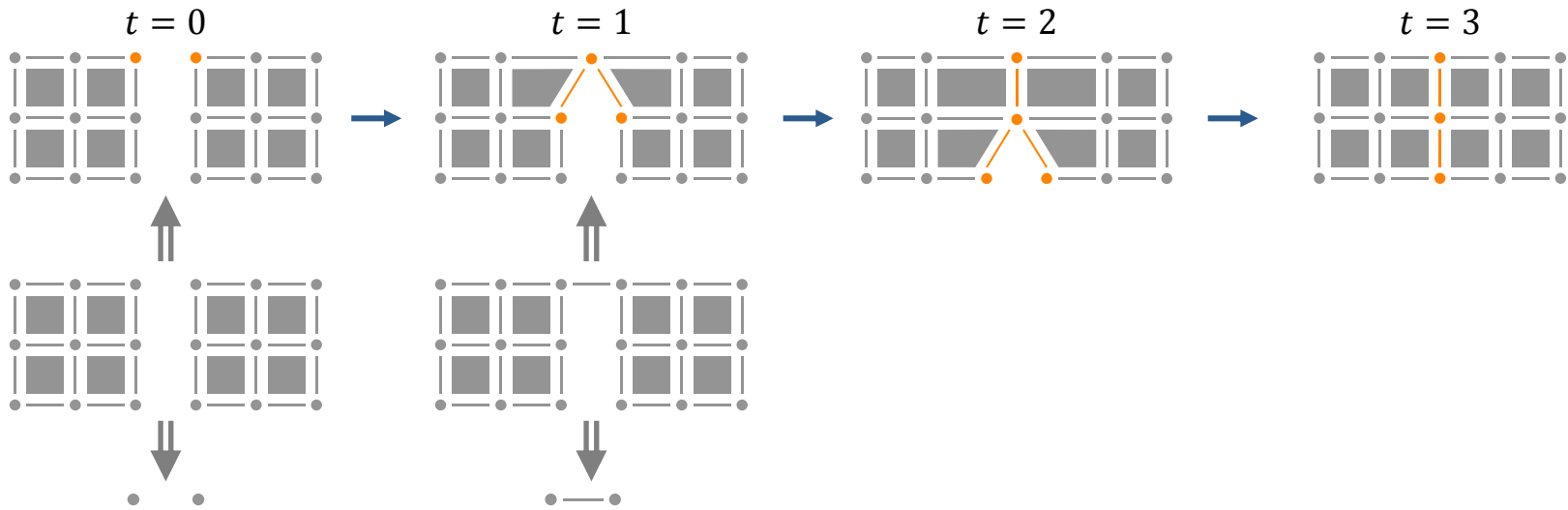


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METHOD: PRINCIPLE

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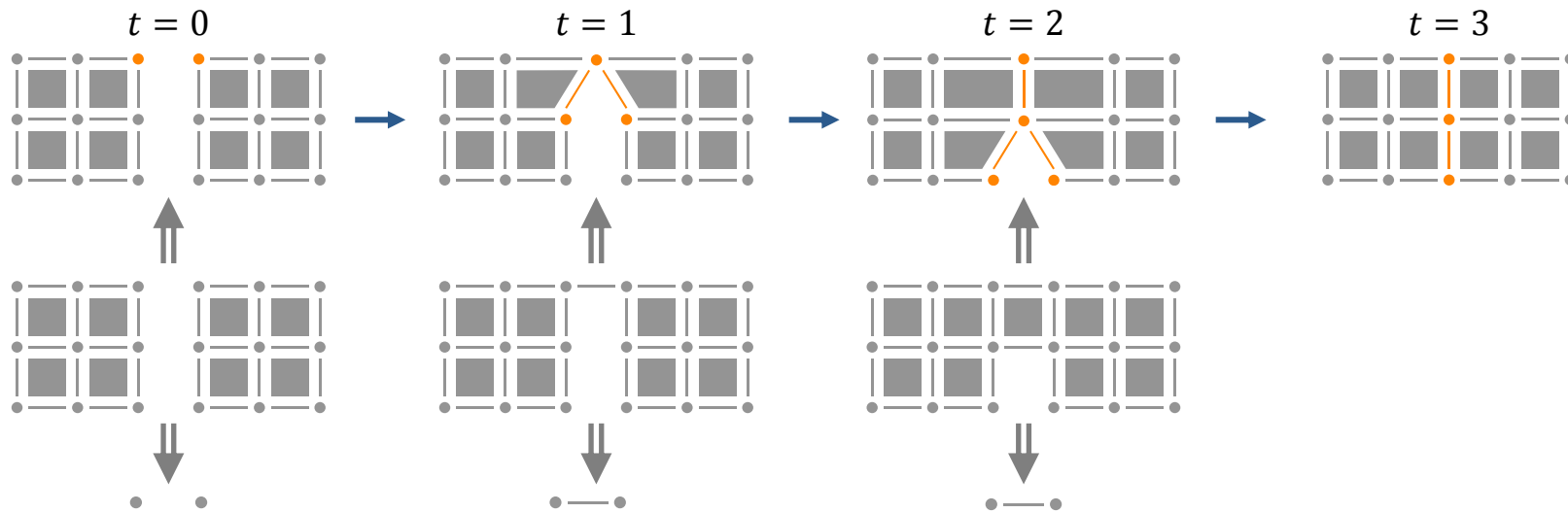


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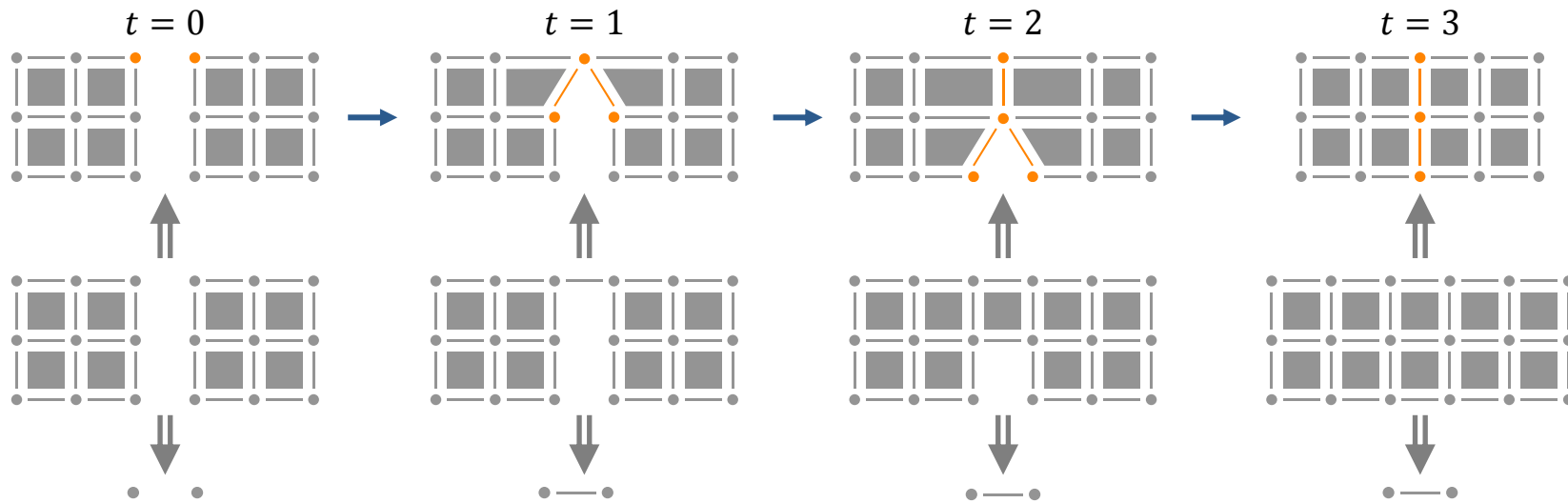


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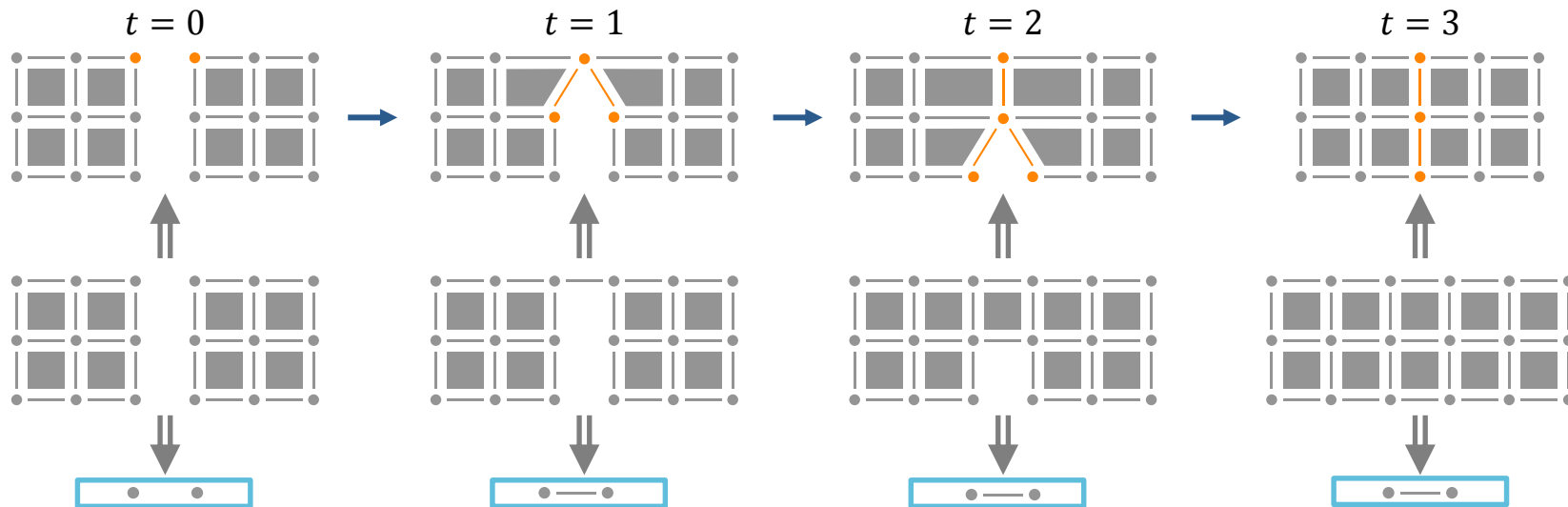


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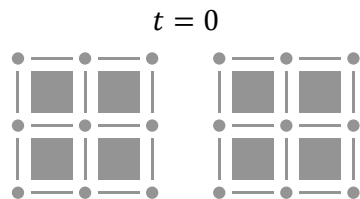


At each step : compute homology on reduced objects

4

METHOD: INITIALIZATION

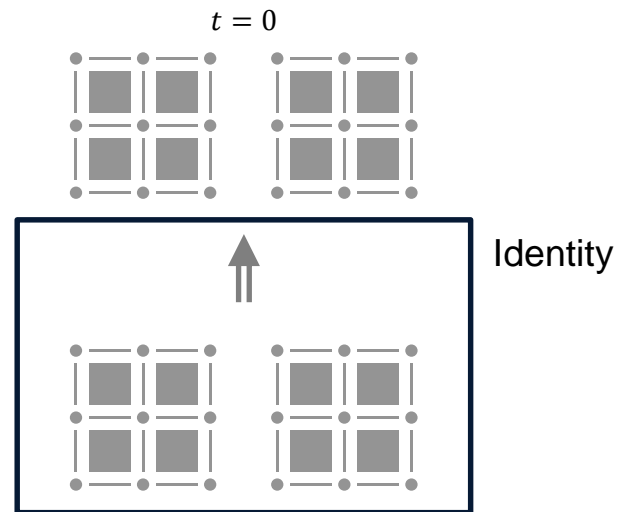
Initial object



4

METHOD: INITIALIZATION

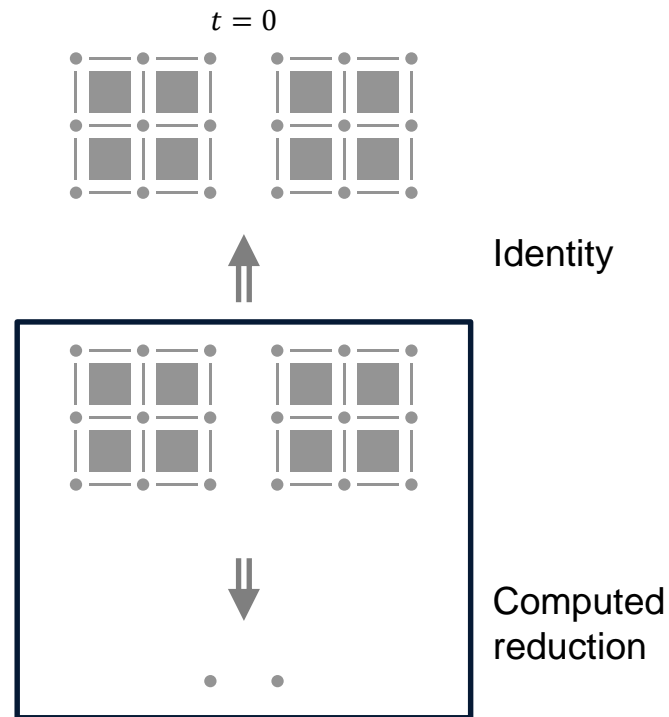
Initial object => build a homological equivalence



4

METHOD: INITIALIZATION

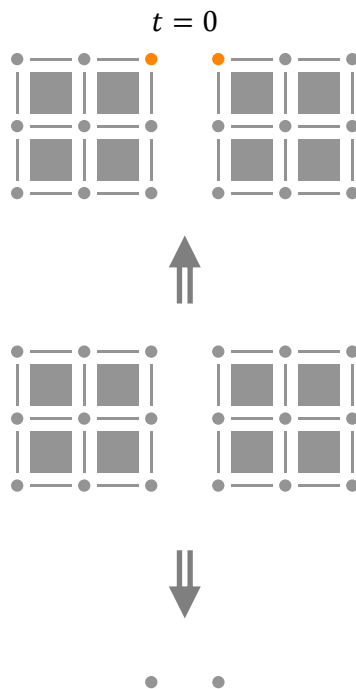
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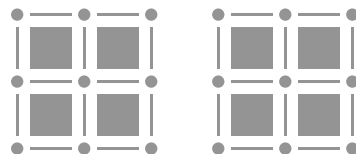
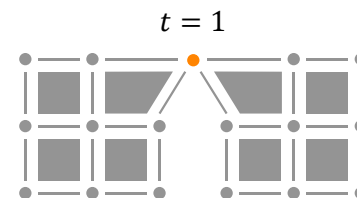
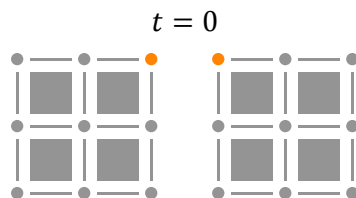
METHOD: WHEN MERGING CELLS



- Operation
- Initialization

4

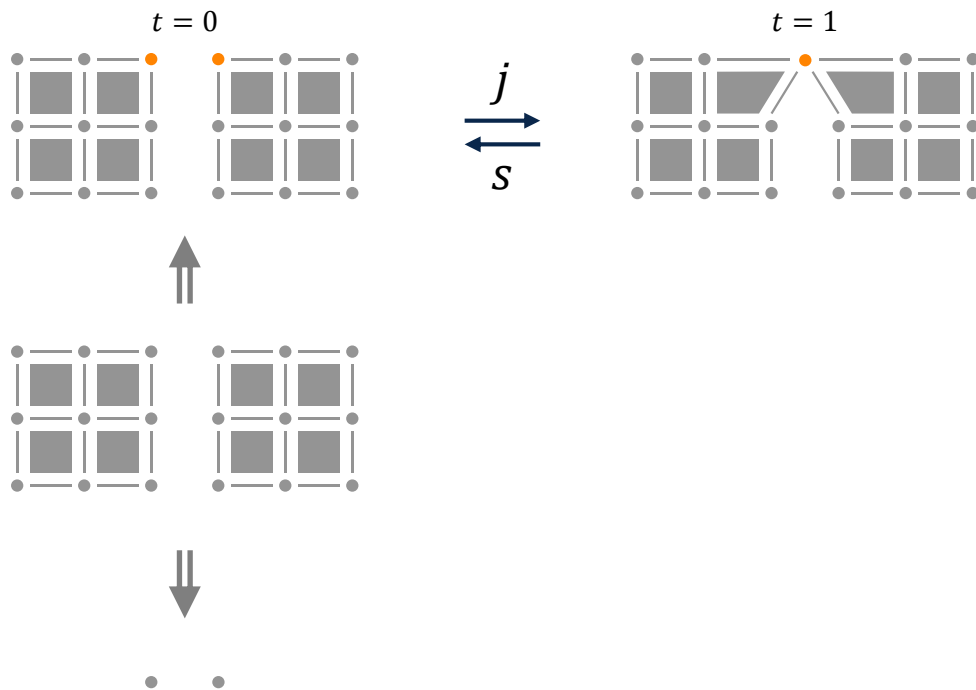
METHOD: WHEN MERGING CELLS



- Operation
- Initialization

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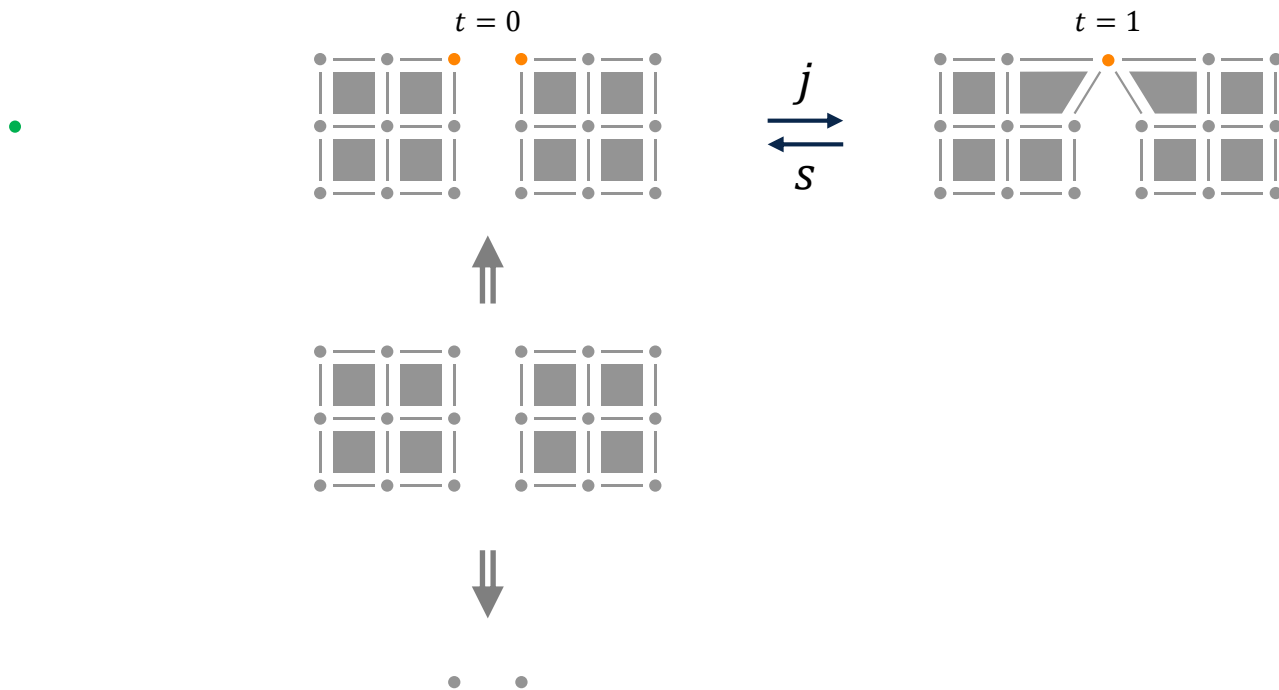
METHOD: WHEN MERGING CELLS



- Orange square: Operation
- Grey square: Initialization

4

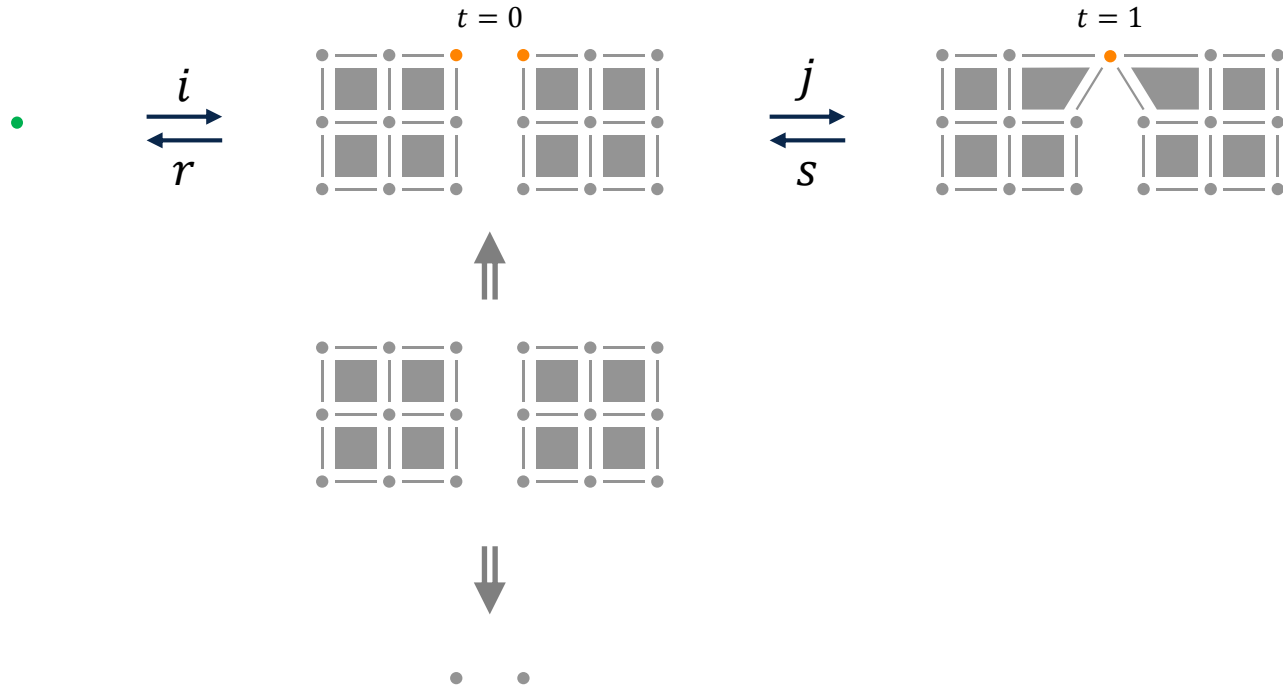
METHOD: WHEN MERGING CELLS



- Operation
- Initialization

4

METHOD: WHEN MERGING CELLS

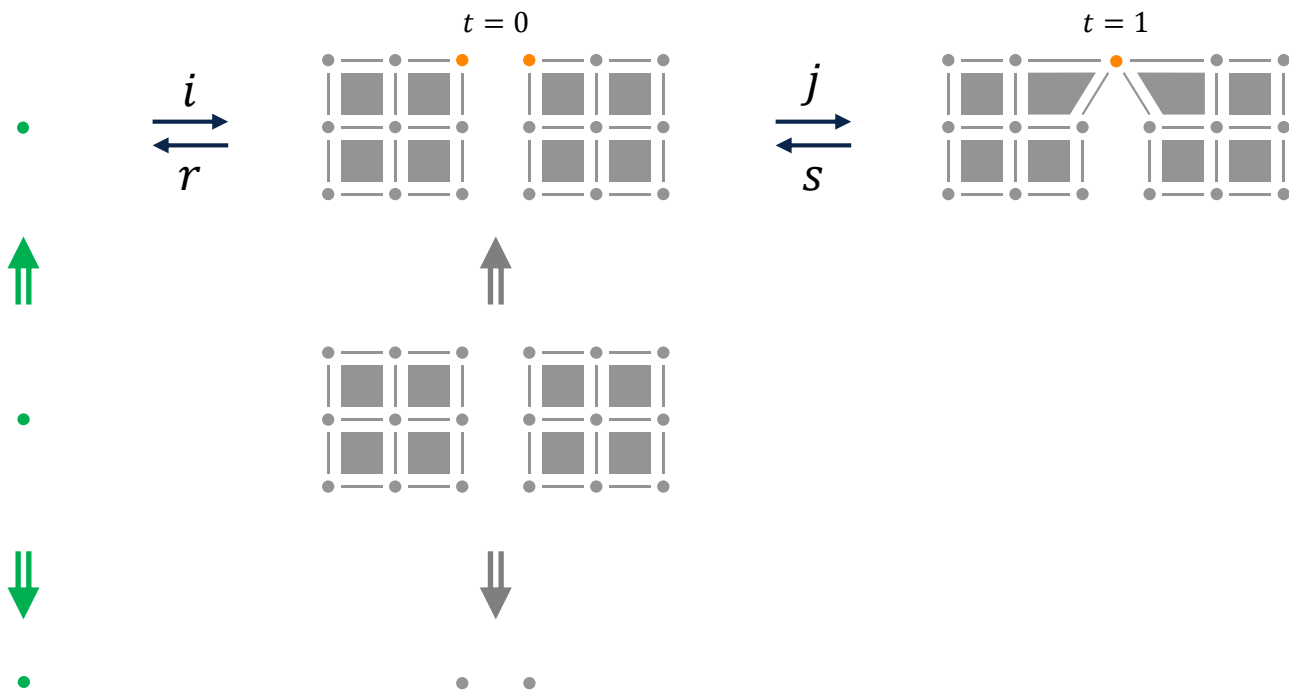


- Operation
- Initialization

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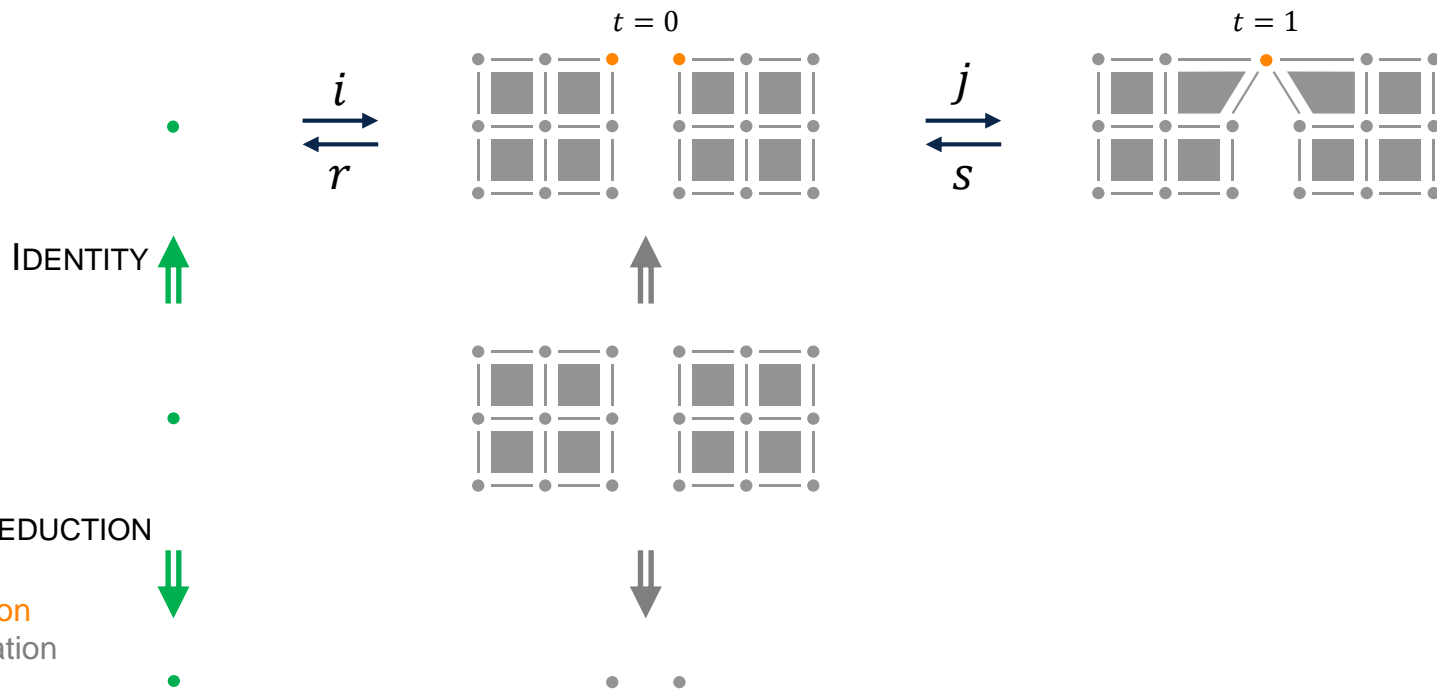
METHOD: WHEN MERGING CELLS



- Operation
- Initialization

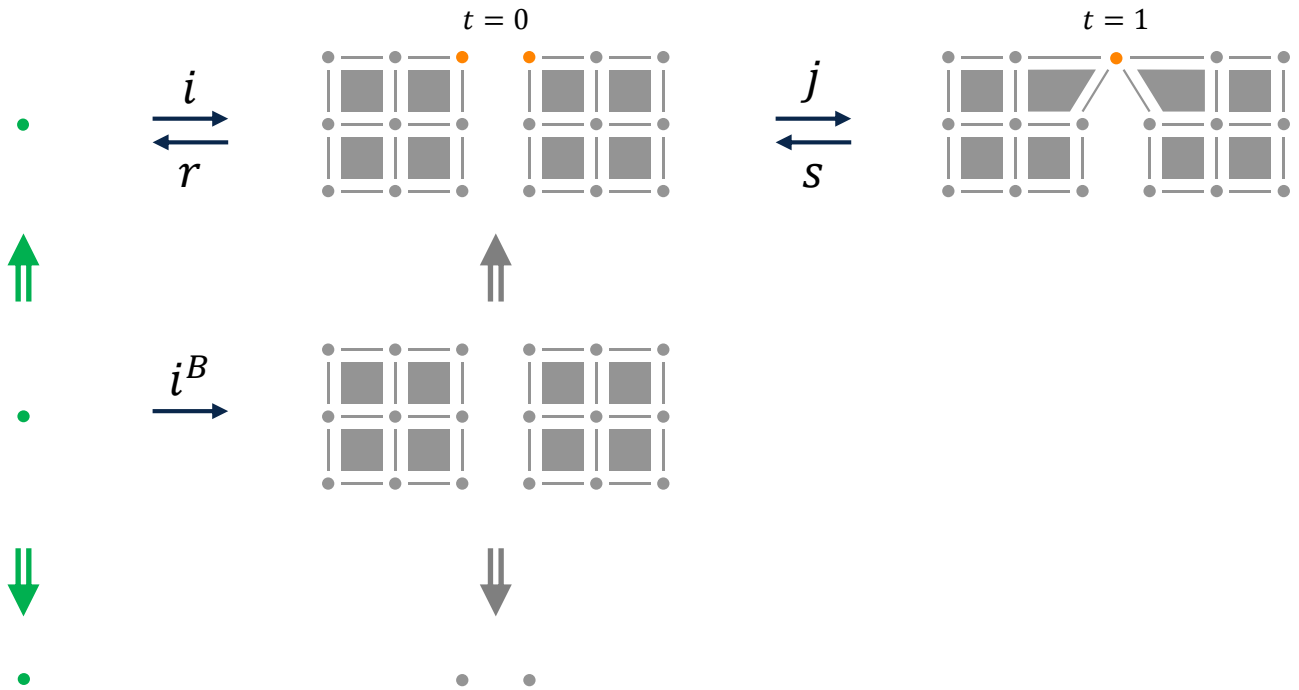
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METHOD: WHEN MERGING CELLS



4

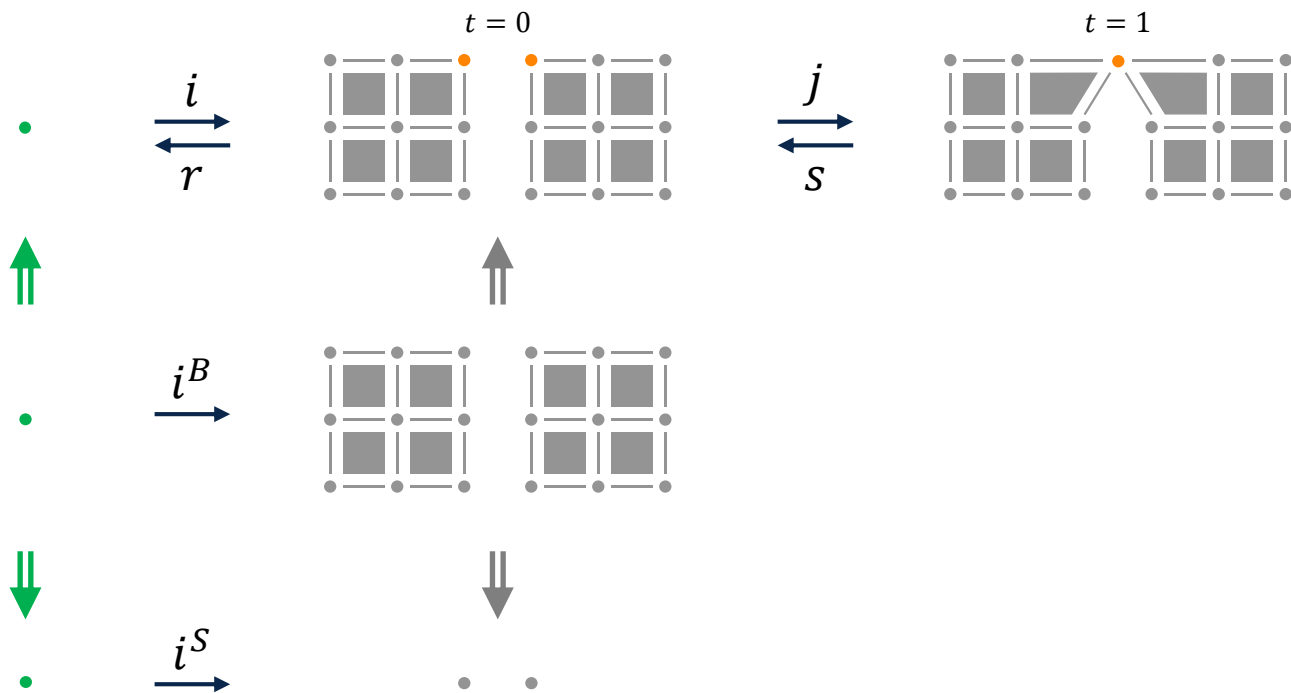
METHOD: WHEN MERGING CELLS



- Operation
- Initialization

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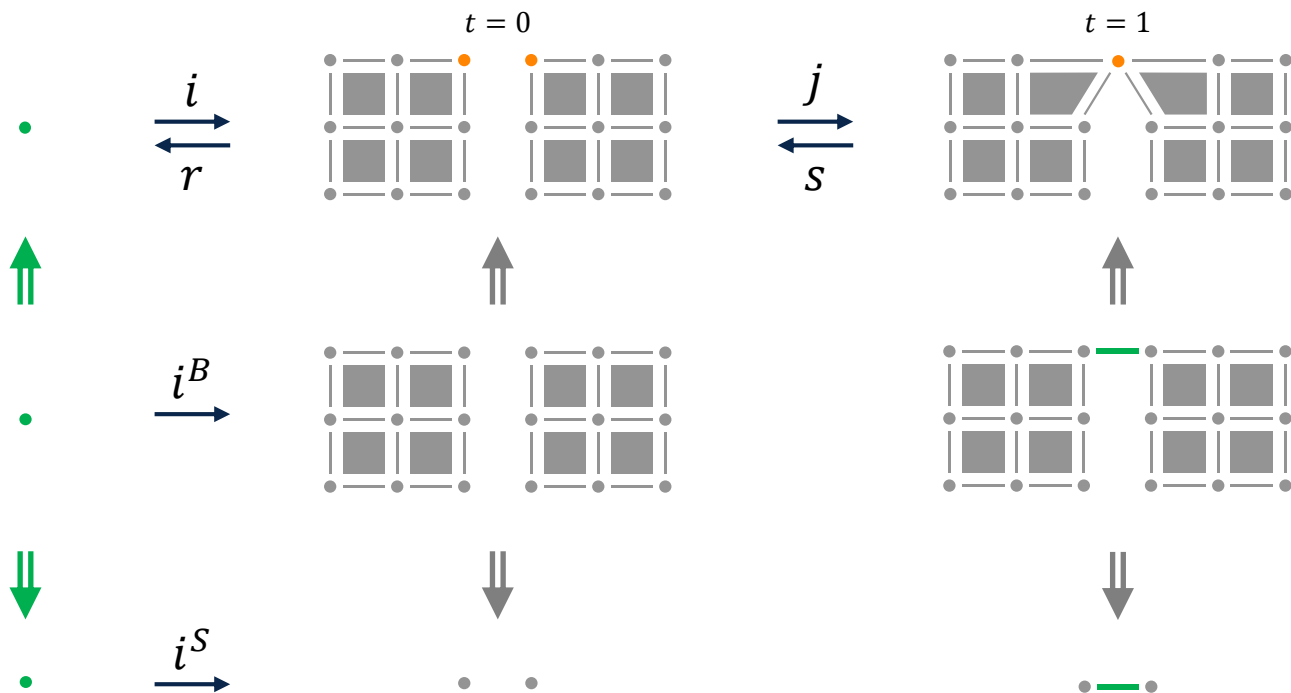
METHOD: WHEN MERGING CELLS



- Operation
- Initialization

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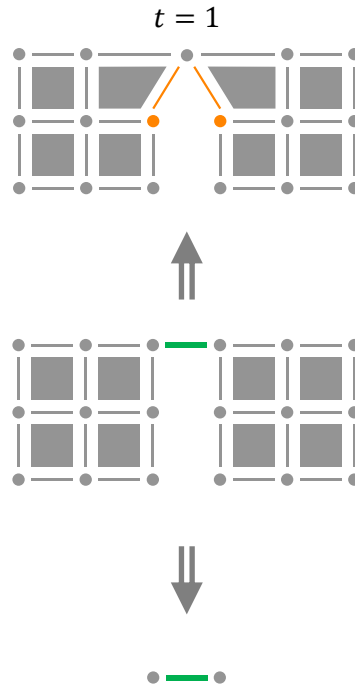
METHOD: WHEN MERGING CELLS



□ Operation
□ Initialization

4

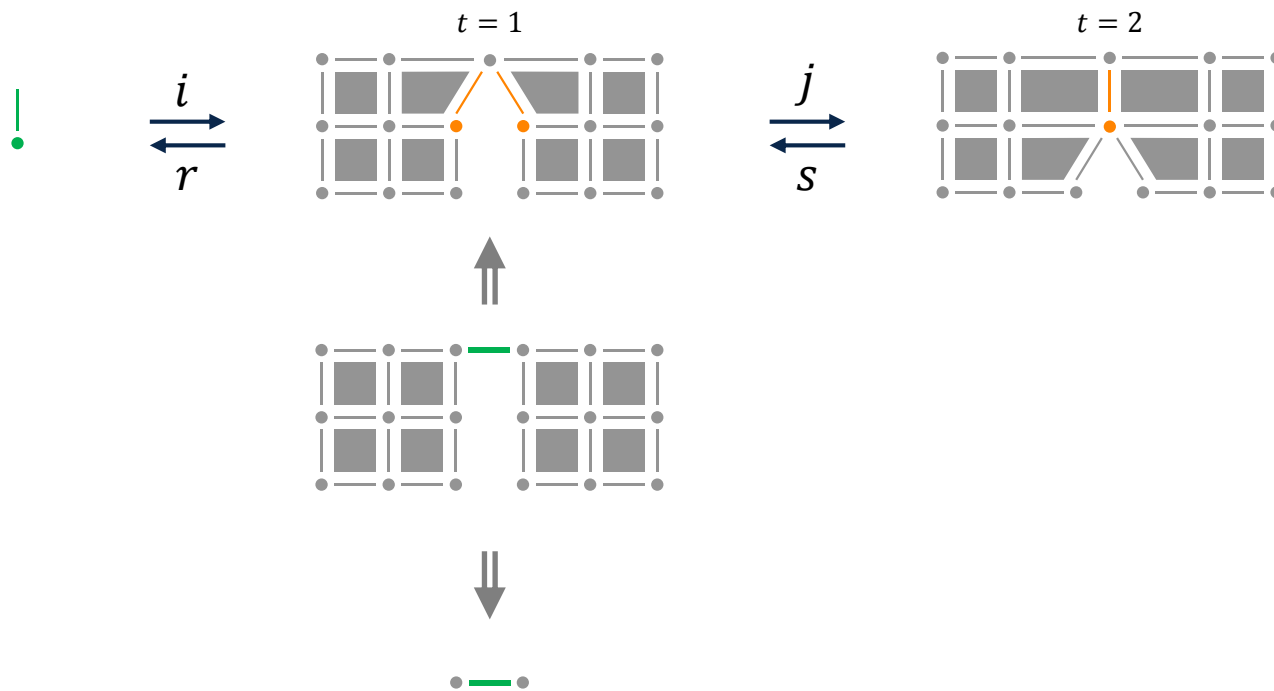
METHOD: WHEN MERGING CELLS



- Operation
- Added complexity
- Initialization

4

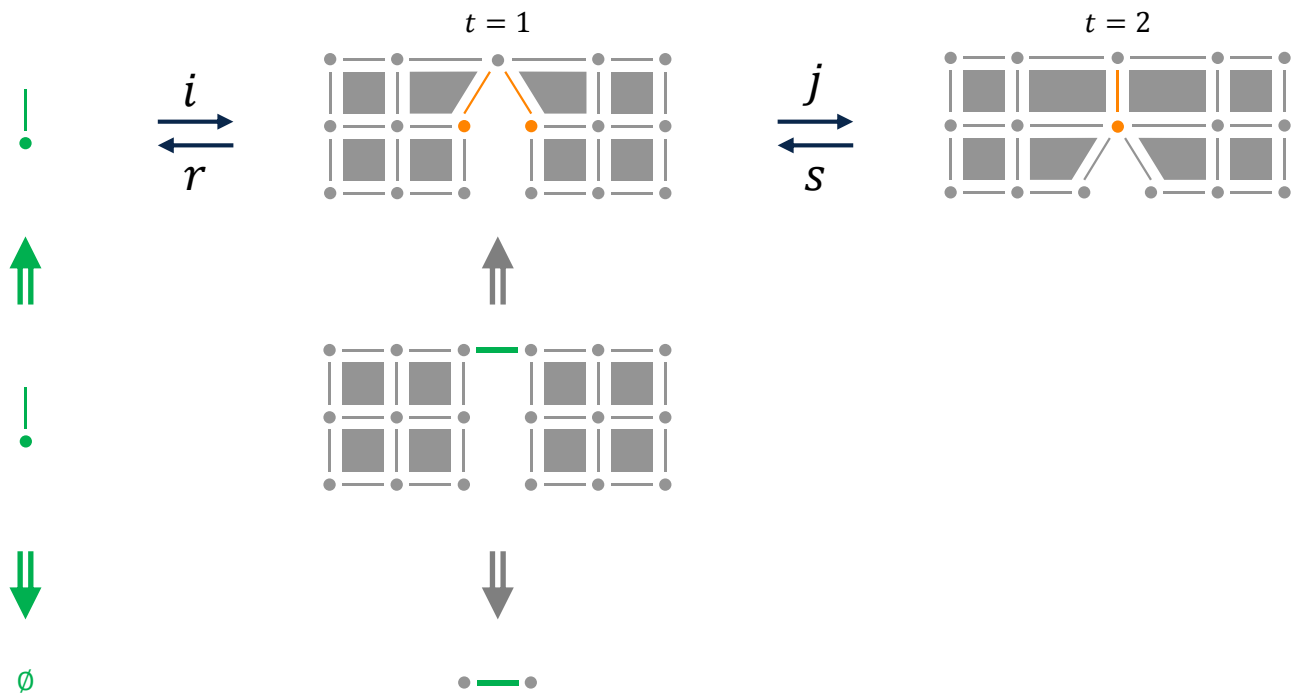
METHOD: WHEN MERGING CELLS



- Operation
- Added complexity
- Initialization

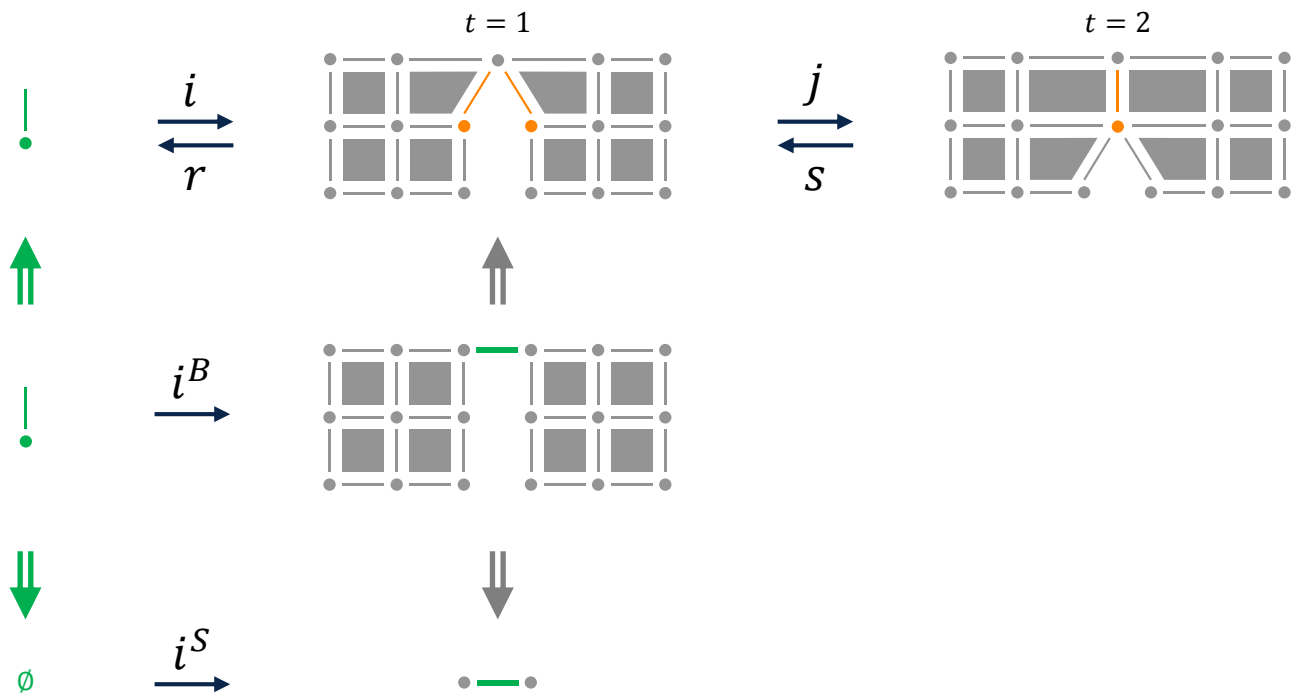
4

METHOD: WHEN MERGING CELLS



4

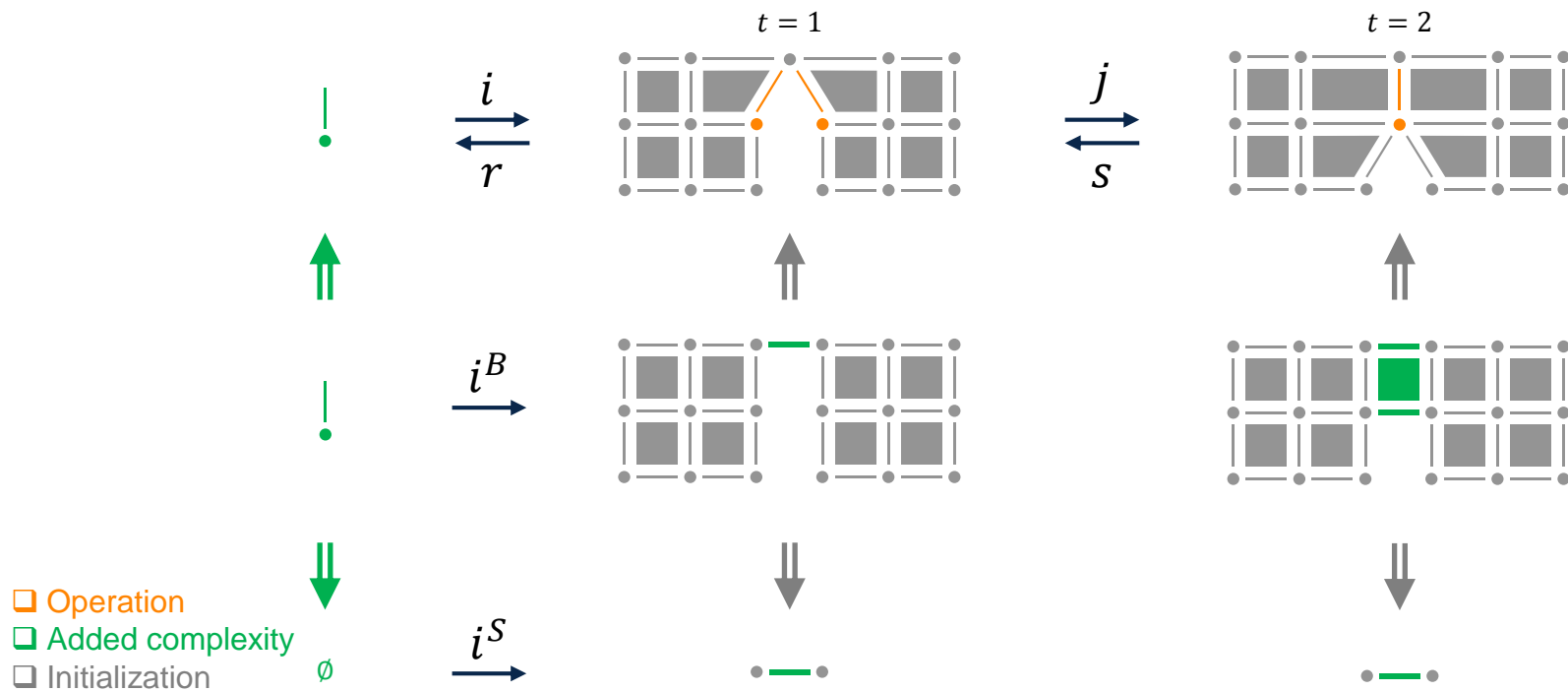
METHOD: WHEN MERGING CELLS



- Operation
- Added complexity
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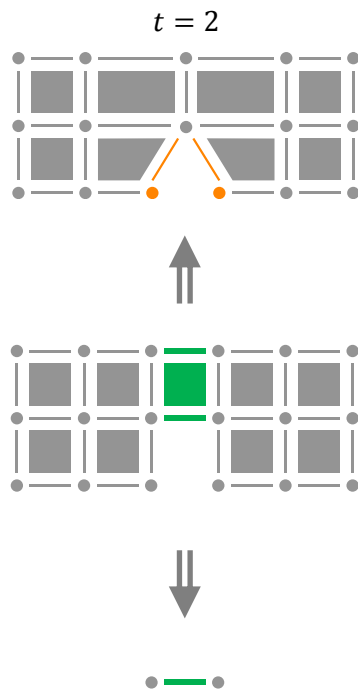
4

METHOD: WHEN MERGING CELLS



4

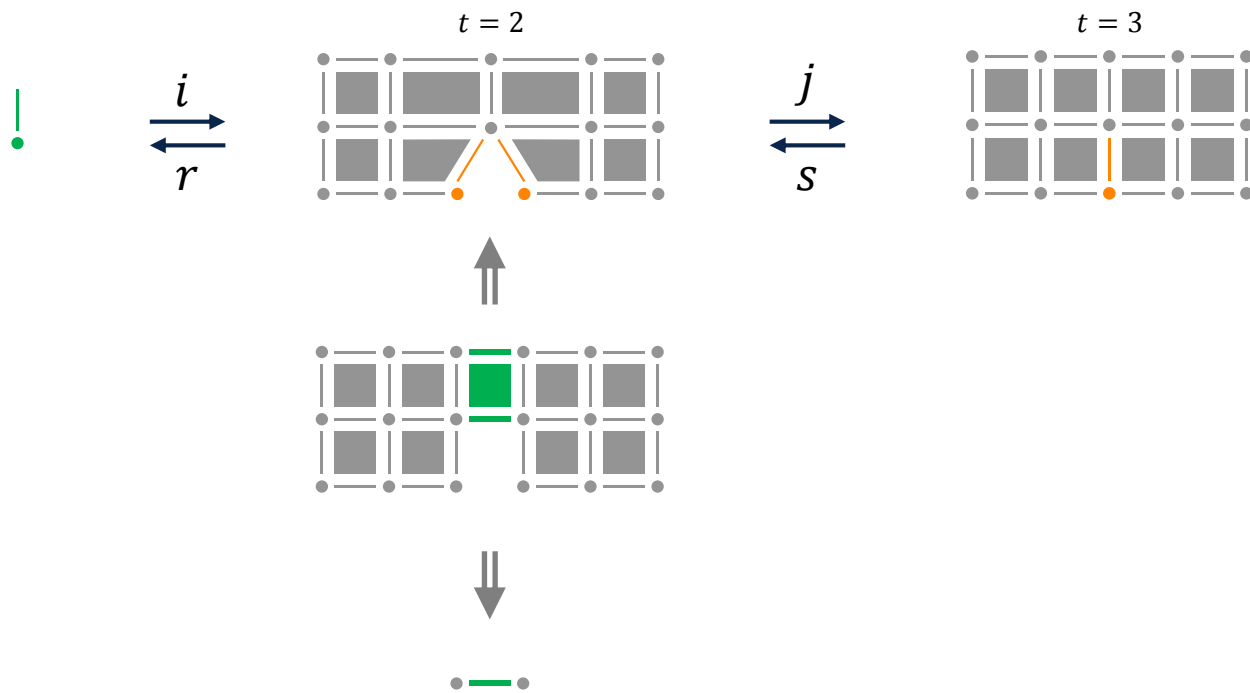
METHOD: WHEN MERGING CELLS



- Operation
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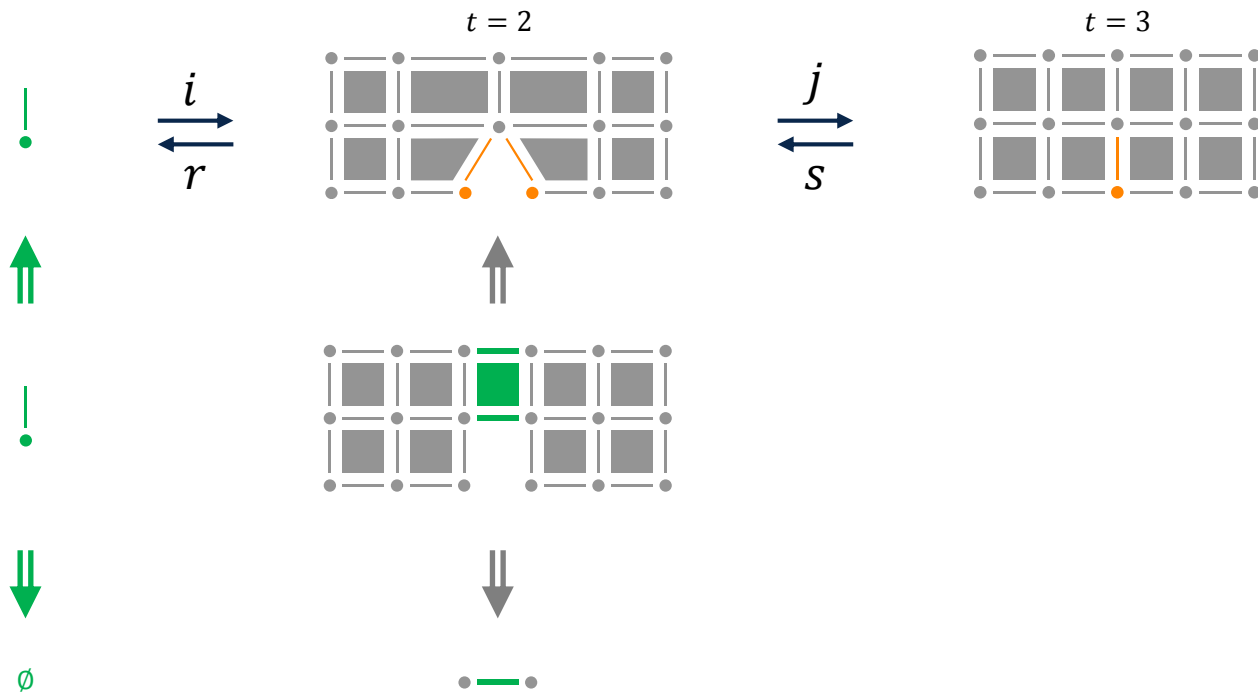
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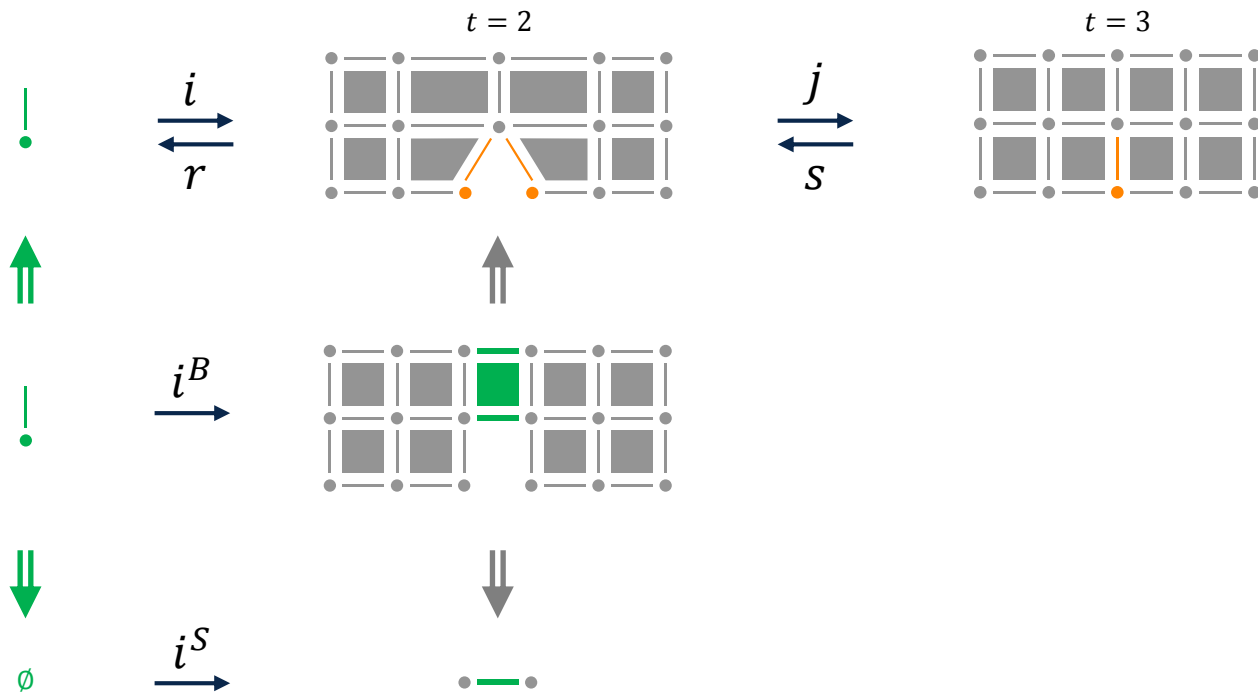
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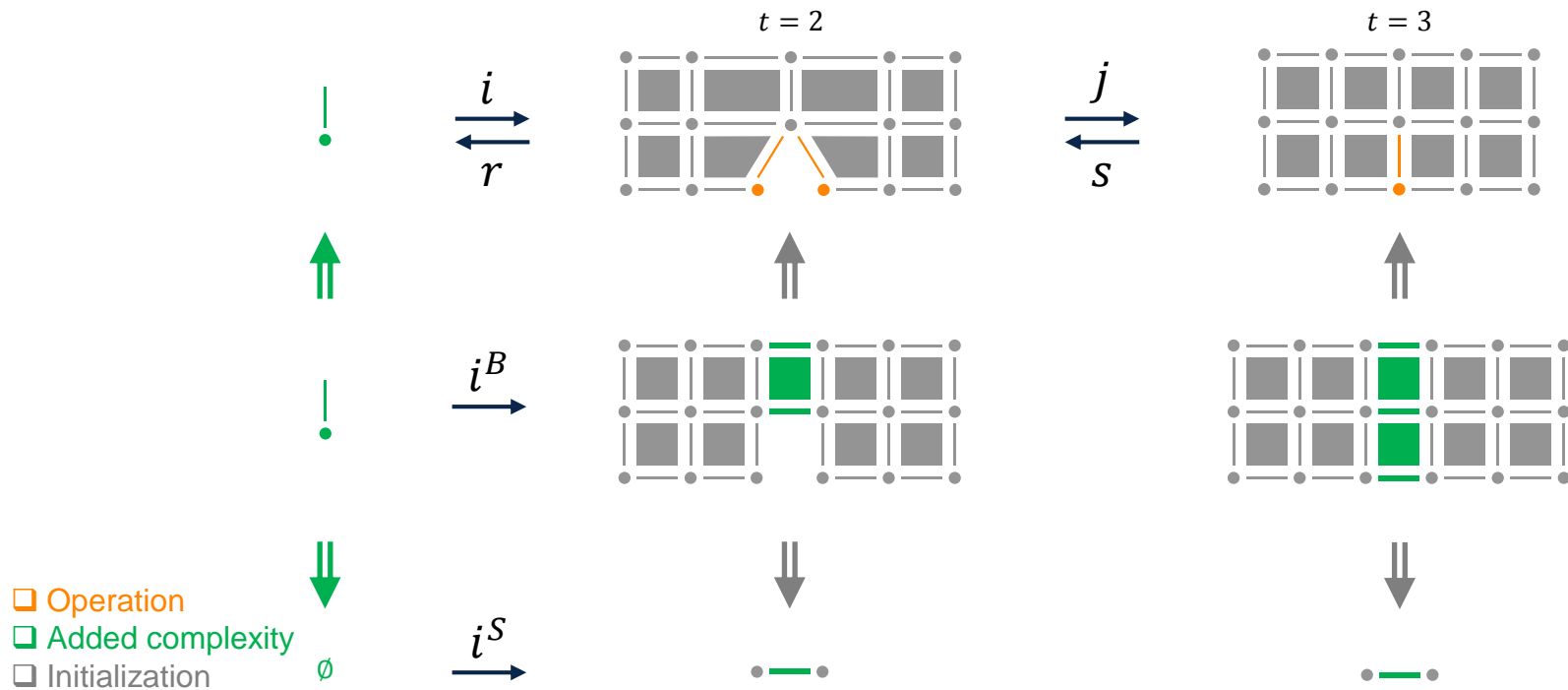
METHOD: WHEN MERGING CELLS



- Operation
- Added complexity
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METHOD: WHEN MERGING CELLS



5: ANALYSIS

5

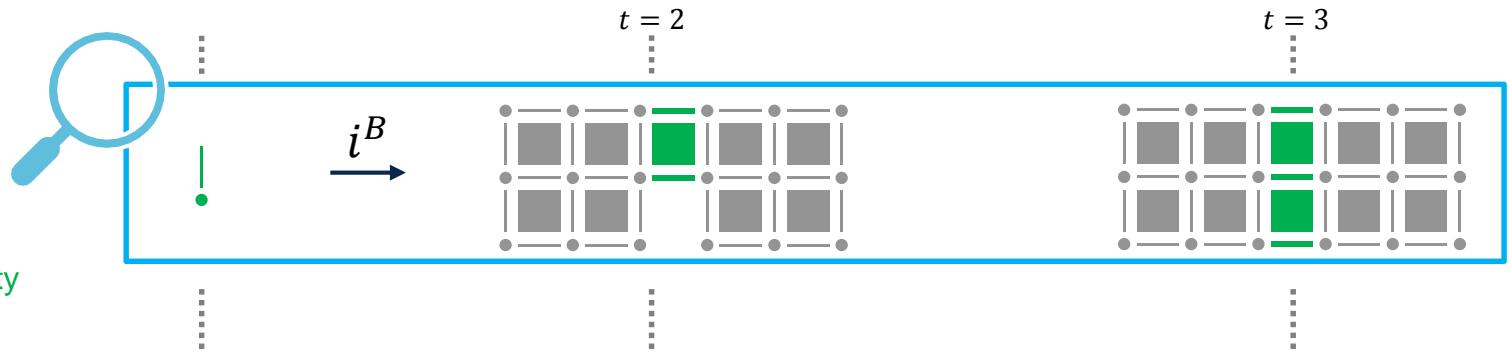
ANALYSIS

Is the computation complexity only related to the complexity of the operated part?

5

FOCUS ON INTERMEDIATE OBJECTS

At step t :



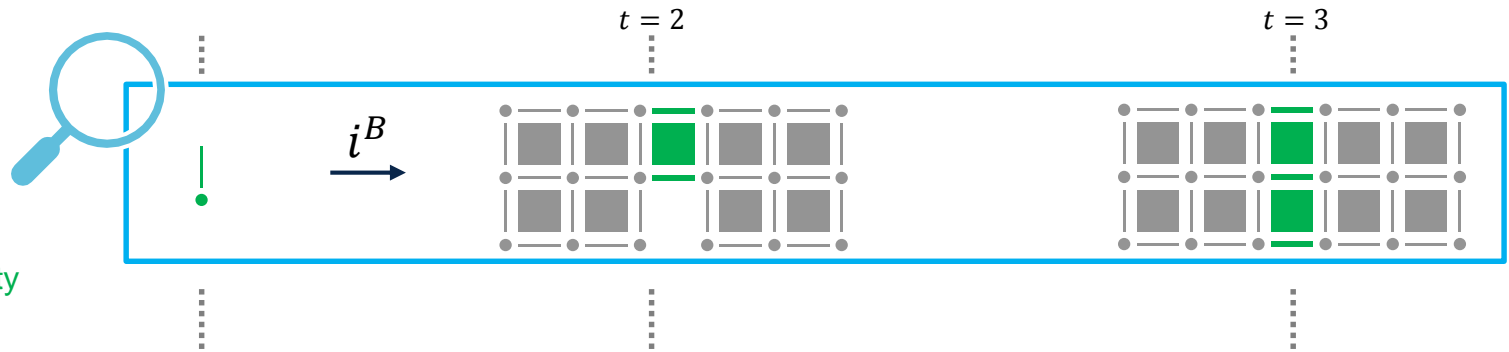
- Added complexity
- Initialization

5

FOCUS ON INTERMEDIATE OBJECTS

At step t :

- Space: object at step $t = \text{initial object} + \sum_{n=1}^t \text{operations representations}$

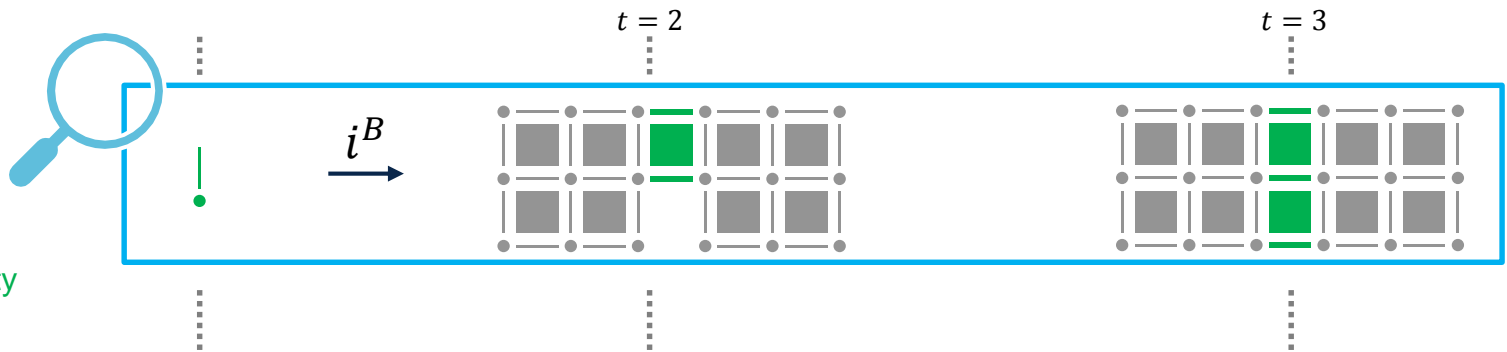


5

FOCUS ON INTERMEDIATE OBJECTS

At step t :

- Space: object at step t = initial object + $\sum_{n=1}^t$ operations representations
- Time: depends only on current step operation : $\partial_{t+1} = \begin{pmatrix} \partial_{op.rep.} & i^B \\ 0 & \partial_t \end{pmatrix}$



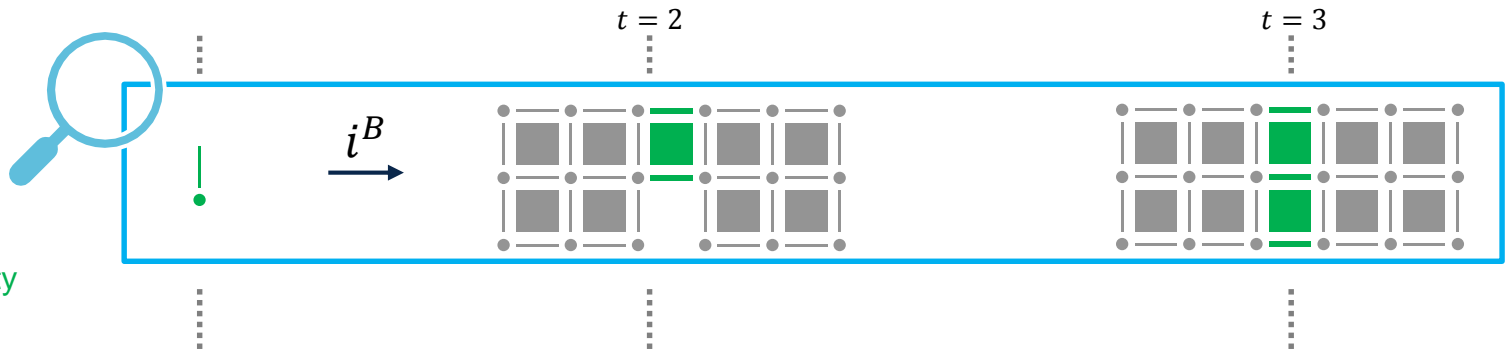
- Added complexity
- Initialization

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FOCUS ON INTERMEDIATE OBJECTS

At step t :

- Space: object at step t = initial object + $\sum_{n=1}^t$ operations representations
- Time: depends only on current step operation : $\partial_{t+1} = \begin{pmatrix} \partial_{op.rep.} & i^B \\ 0 & \partial_t \end{pmatrix}$
- Possible loss of locality browsing ∂_t to construct ∂_{t+1} : \Rightarrow Construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with a complexity depending only on A,B,C



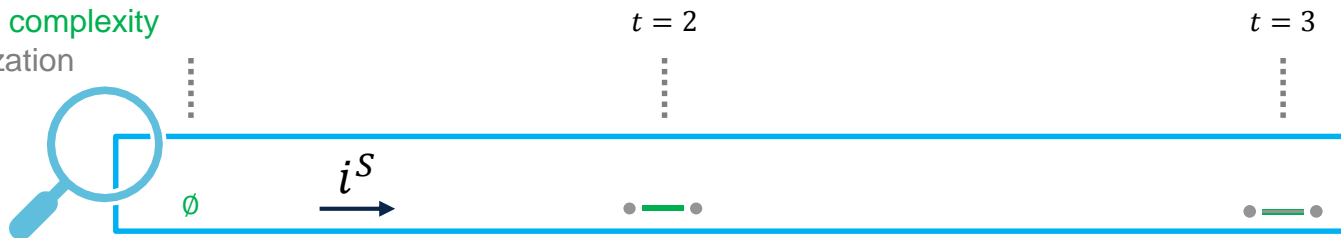
- Added complexity
- Initialization

5

FOCUS ON REDUCED OBJECTS

EXACTLY THE SAME BEHAVIOR than intermediate objects.

- Added complexity
- Initialization



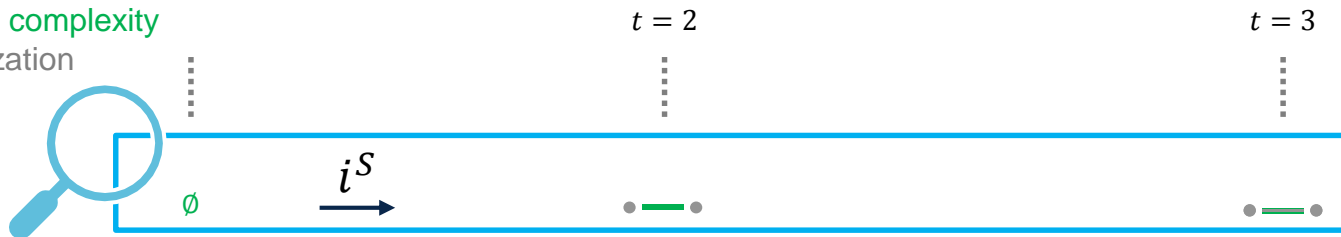
5

FOCUS ON REDUCED OBJECTS

EXACTLY THE SAME BEHAVIOR than intermediate objects. At step t :

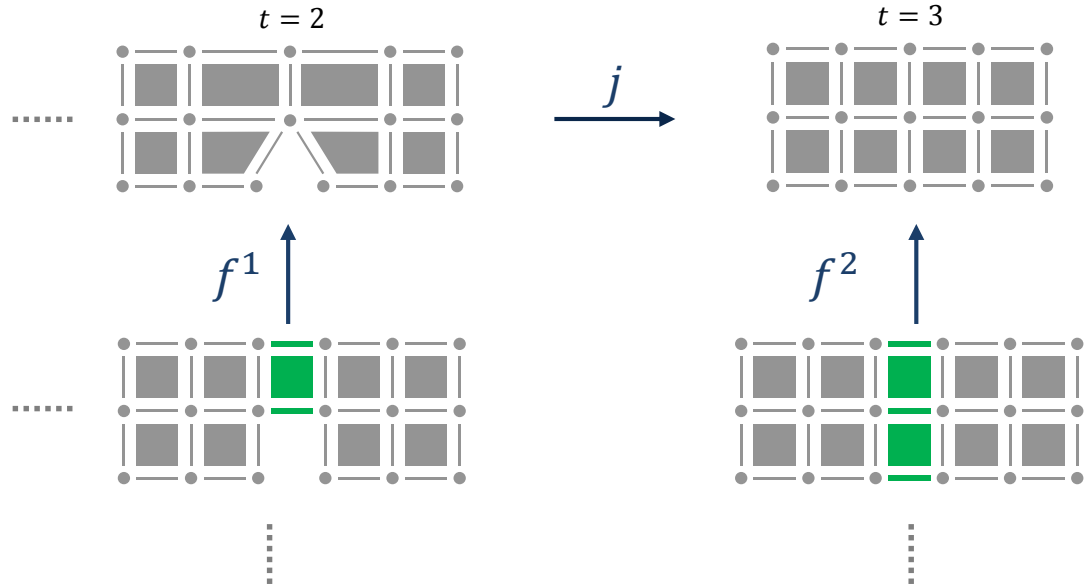
- Space: object at step $t =$ initial object $+ \sum_{n=1}^t$ operations representations
- Time: depends only on current step operation : $\partial_{t+1} = \begin{pmatrix} \partial_{op.rep.} & i^S \\ 0 & \partial_t \end{pmatrix}$
- Possible loss of locality browsing ∂_t to construct ∂_{t+1} : \Rightarrow Construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with a complexity depending only on A,B,C

- Added complexity
- Initialization



5

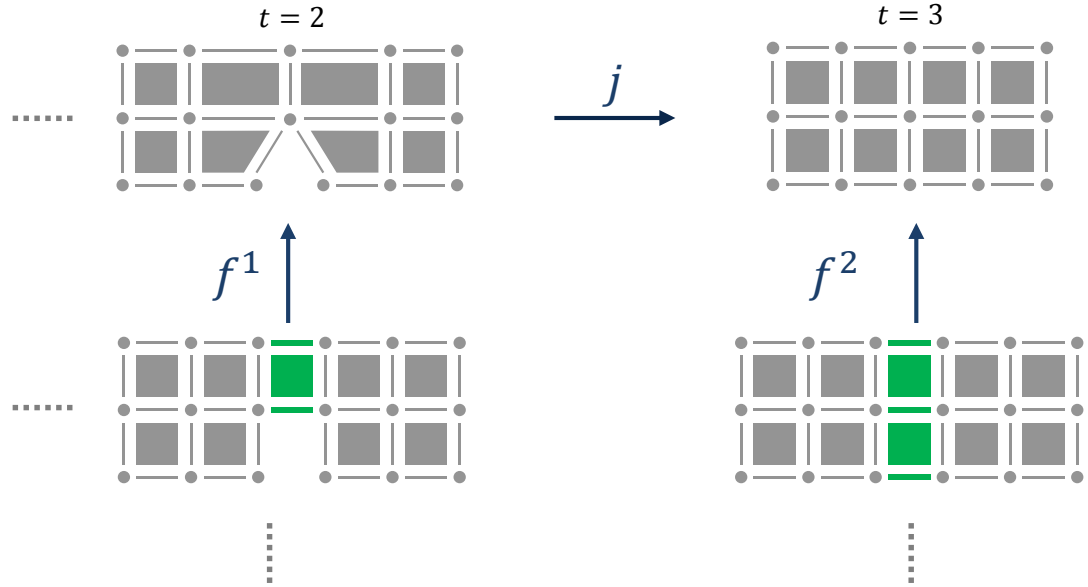
FOCUS ON f COMPLEXITY



5

FOCUS ON f COMPLEXITY

$$f^2 = \begin{pmatrix} 0 \\ f^1 j \end{pmatrix}$$



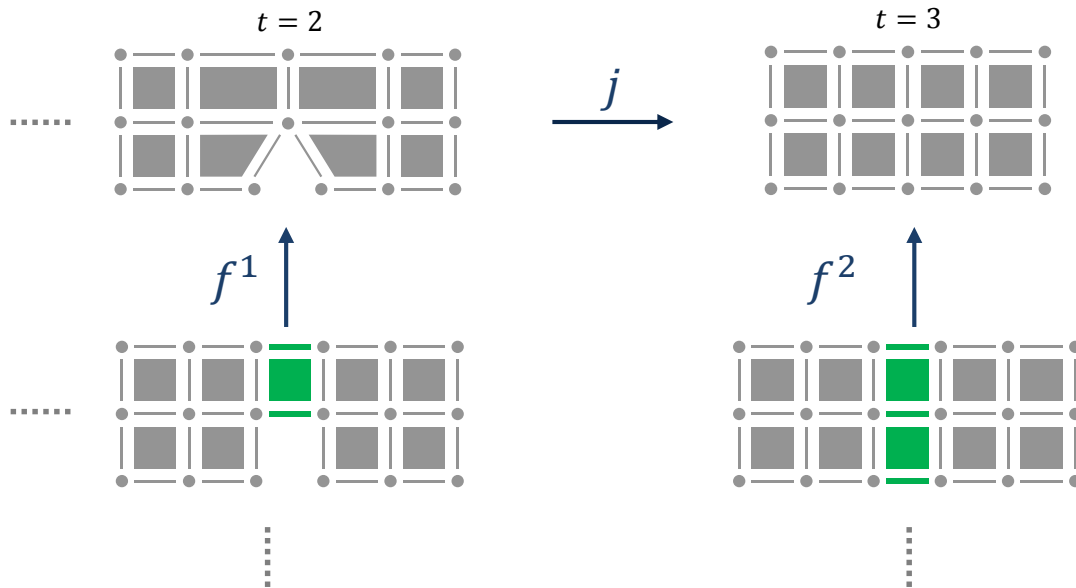
- Added complexity
- Initialization complexity

5

FOCUS ON f COMPLEXITY

$$f^2 = \begin{pmatrix} 0 \\ f^{1j} \end{pmatrix}$$

Possible loss of locality: f^{1j}



- Added complexity
- Initialization complexity

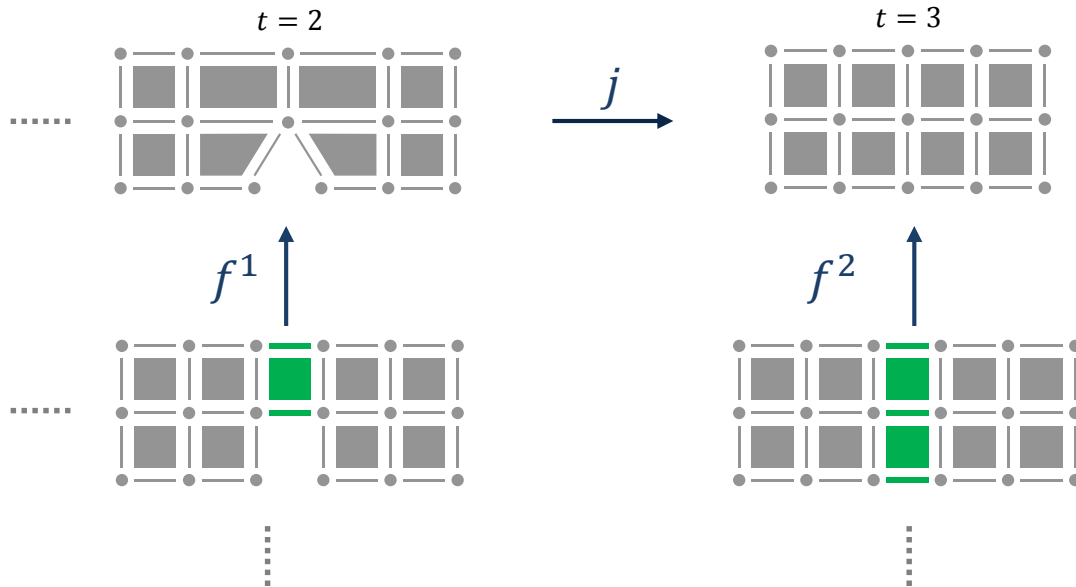
5

FOCUS ON f COMPLEXITY

$$f^2 = \begin{pmatrix} 0 \\ f^1 j \end{pmatrix}$$

Possible loss of locality: $f^1 j$

- Identity + Variations

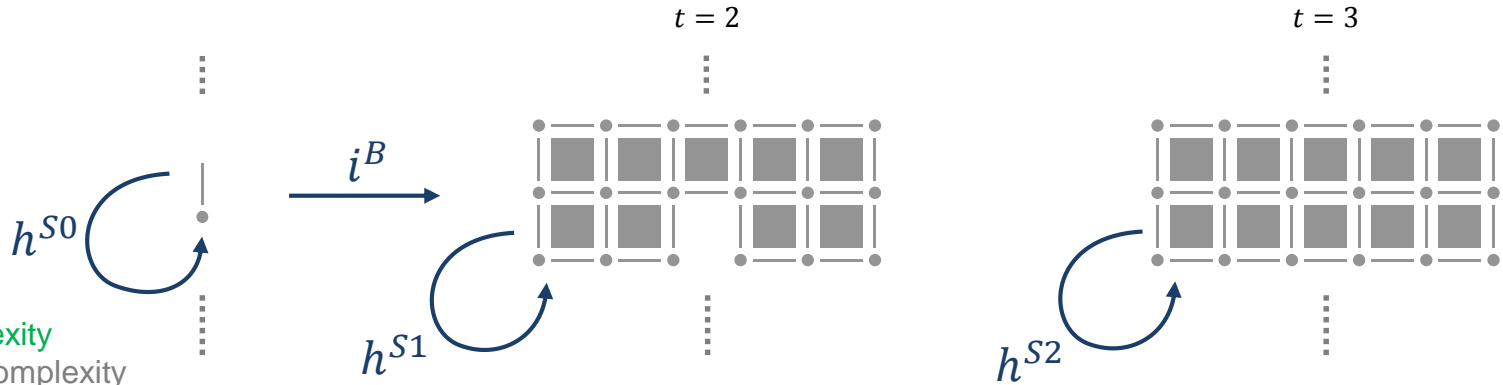


- Added complexity
- Initialization complexity

5

FOCUS ON h^S COMPLEXITY

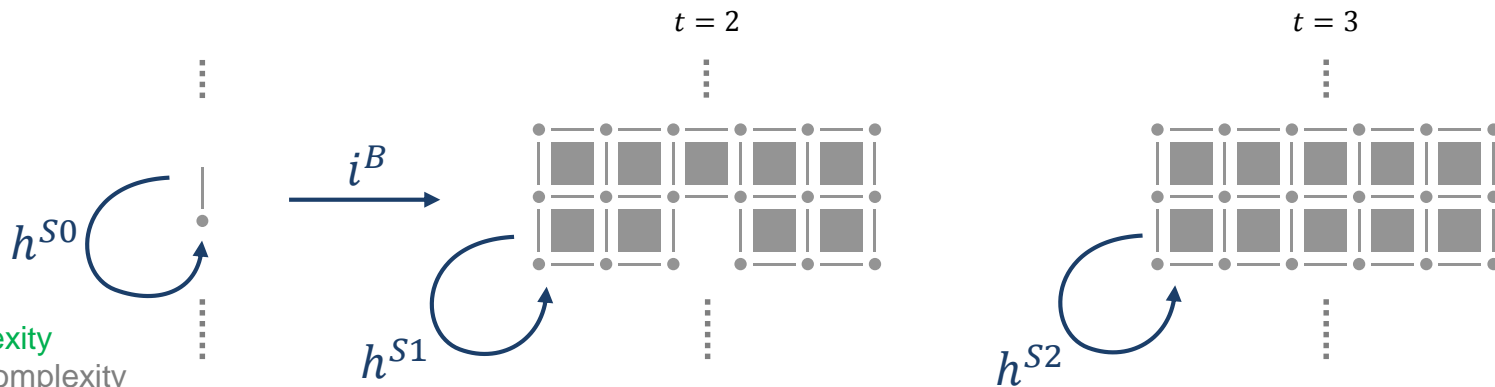
- Added complexity
- Initialization complexity



5

FOCUS ON h^S COMPLEXITY

$$h^{S2} = \begin{pmatrix} -h^{S0} & h^{S0} i^B h^{S1} \\ 0 & h^{S1} \end{pmatrix}$$



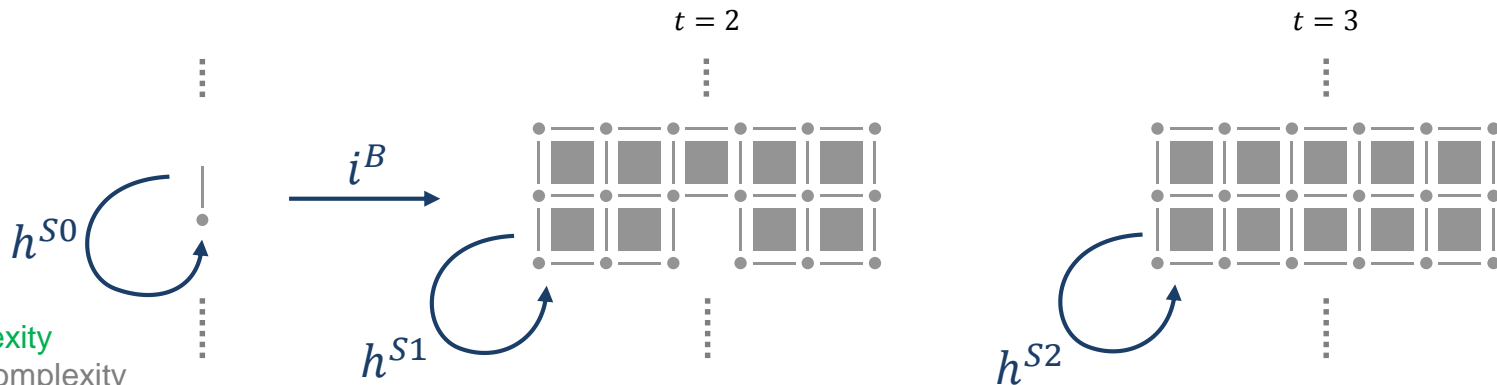
5

FOCUS ON h^S COMPLEXITY

Possible loss of locality: browsing h^{S1} for h^{S2} construction

$$h^{S2} = \begin{pmatrix} -h^{S0} & h^{S0} i^B h^{S1} \\ 0 & h^{S1} \end{pmatrix}$$

- Added complexity
- Initialization complexity

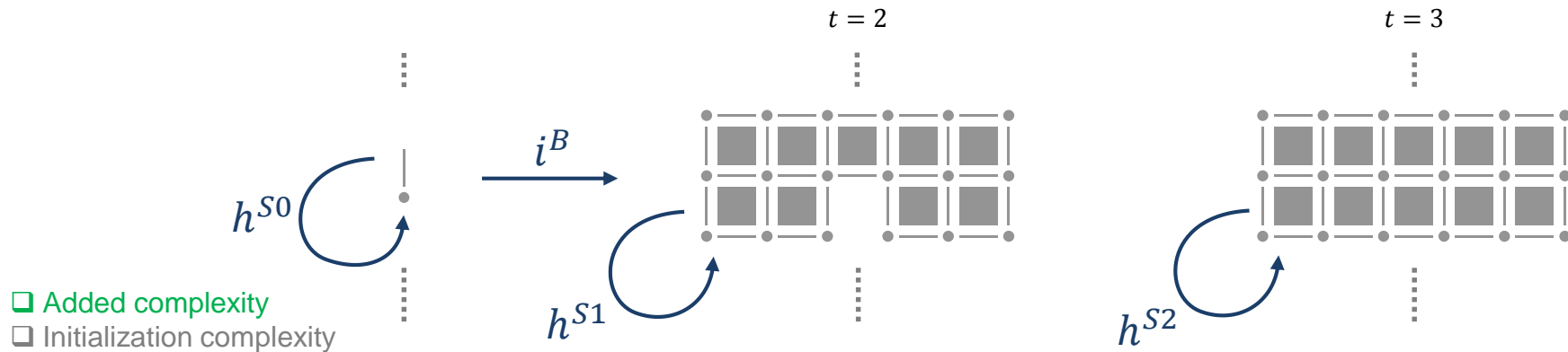


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FOCUS ON h^S COMPLEXITY

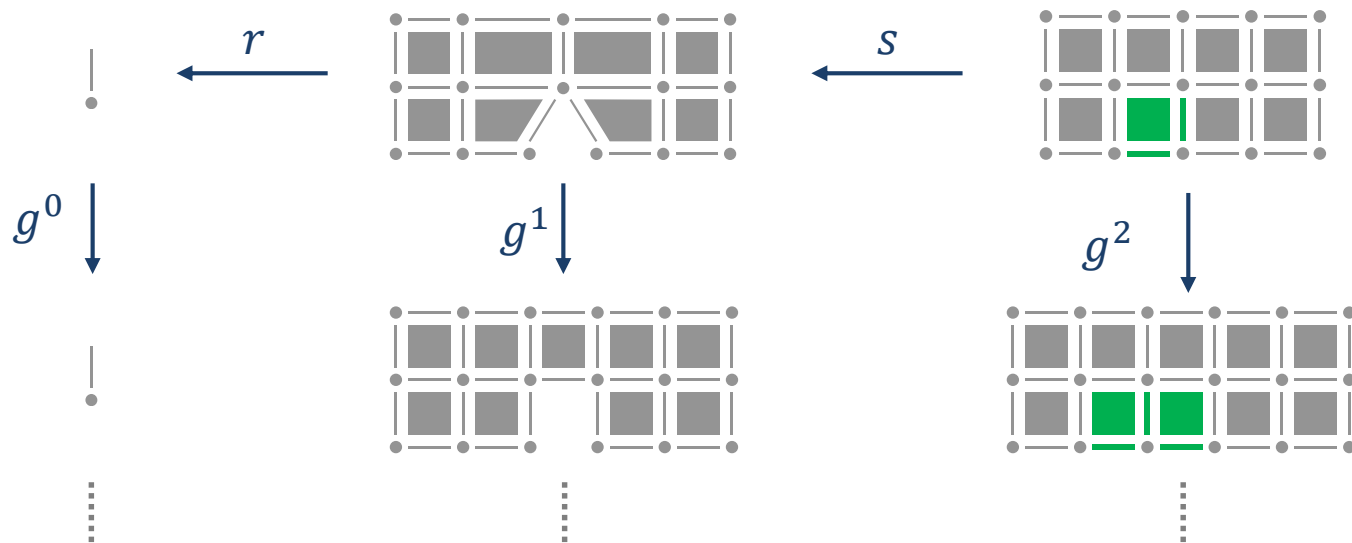
Possible loss of locality: browsing h^{S1} for h^{S2} construction

$$h^{S2} = \begin{pmatrix} -h^{S0} & h^{S0} i^B h^{S1} \\ 0 & h^{S1} \end{pmatrix} \Rightarrow \text{Construct } \begin{pmatrix} A & B \\ C & D \end{pmatrix} \text{ with a complexity depending only on A,B,C}$$



5

FOCUS ON g COMPLEXITY

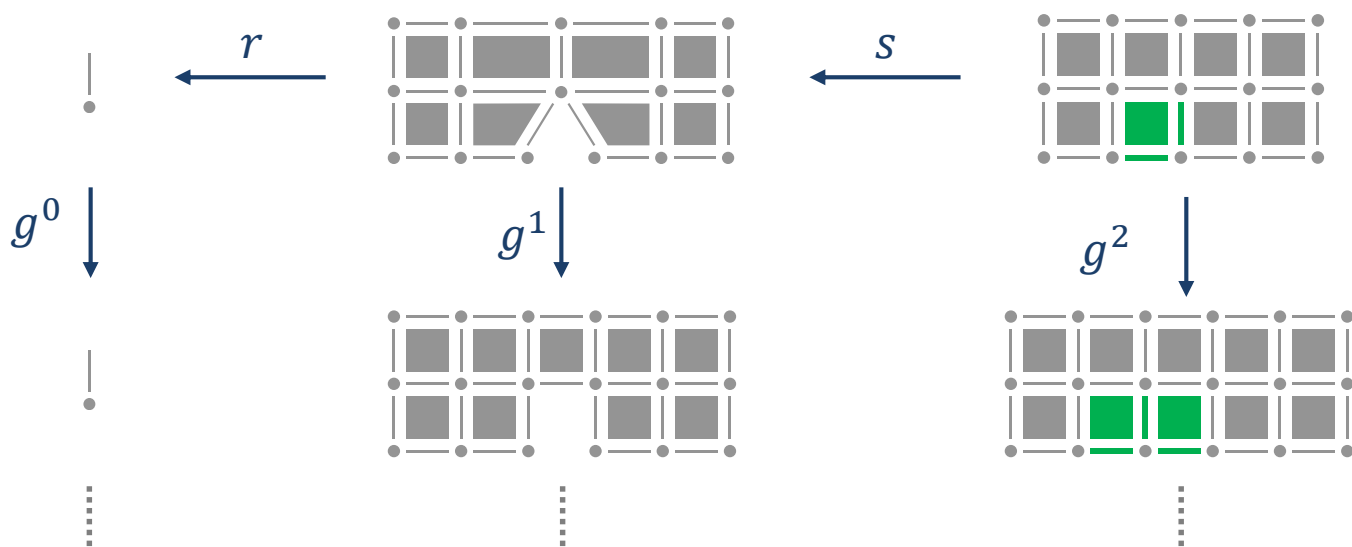


- Added complexity
- Initialization complexity

5

FOCUS ON g COMPLEXITY

$$g^2 = (-s\partial^1 r g^0 \quad s g^1)$$



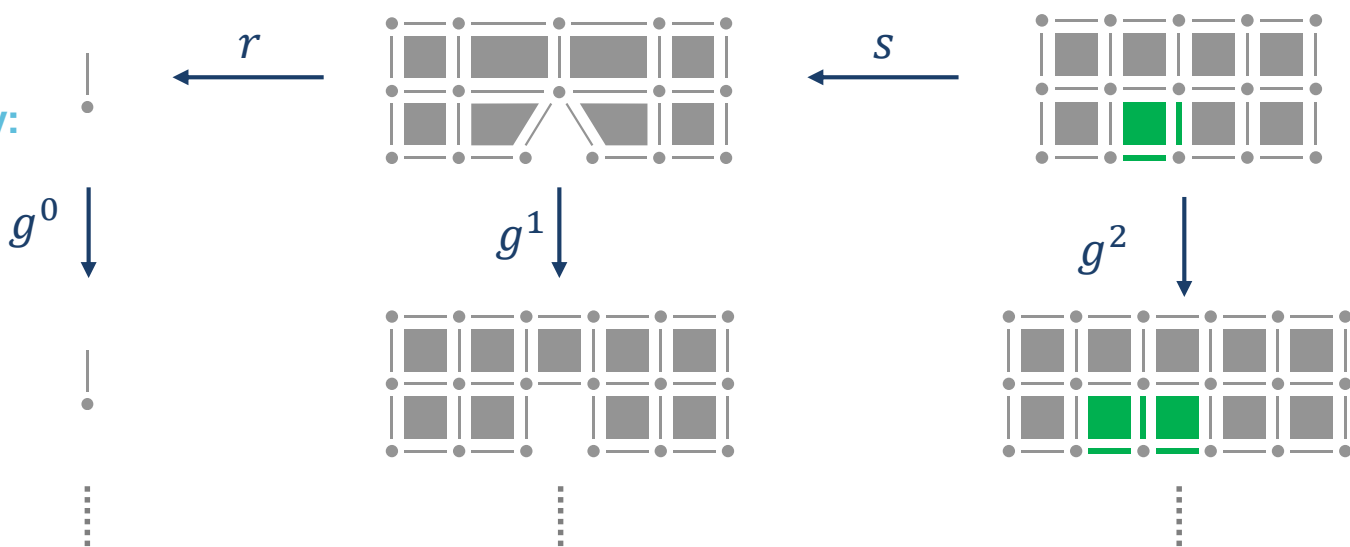
- Added complexity
- Initialization complexity

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FOCUS ON g COMPLEXITY

$$g^2 = (-s\partial^1 r g^0 \quad s g^1)$$

Possible loss of locality:
 $s g^1$



- Added complexity
- Initialization complexity

5

FOCUS ON g COMPLEXITY

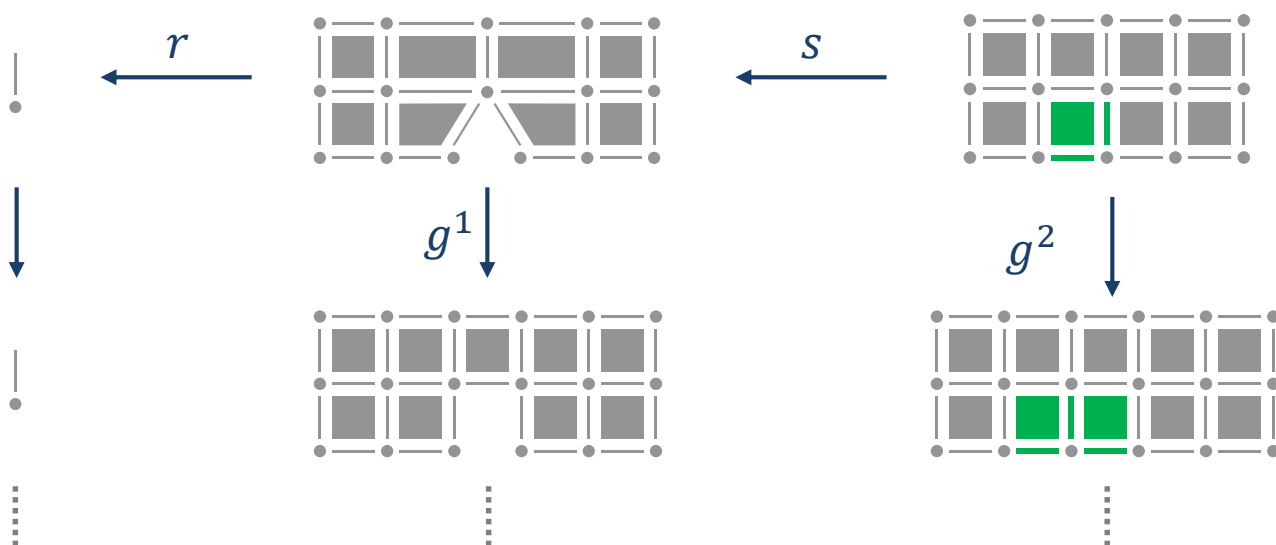
$$g^2 = (-s\partial^1 r g^0 \quad s g^1)$$

Possible loss of locality:
 sg^1

- Identity + Variations

g^0

- Added complexity
- Initialization complexity



5

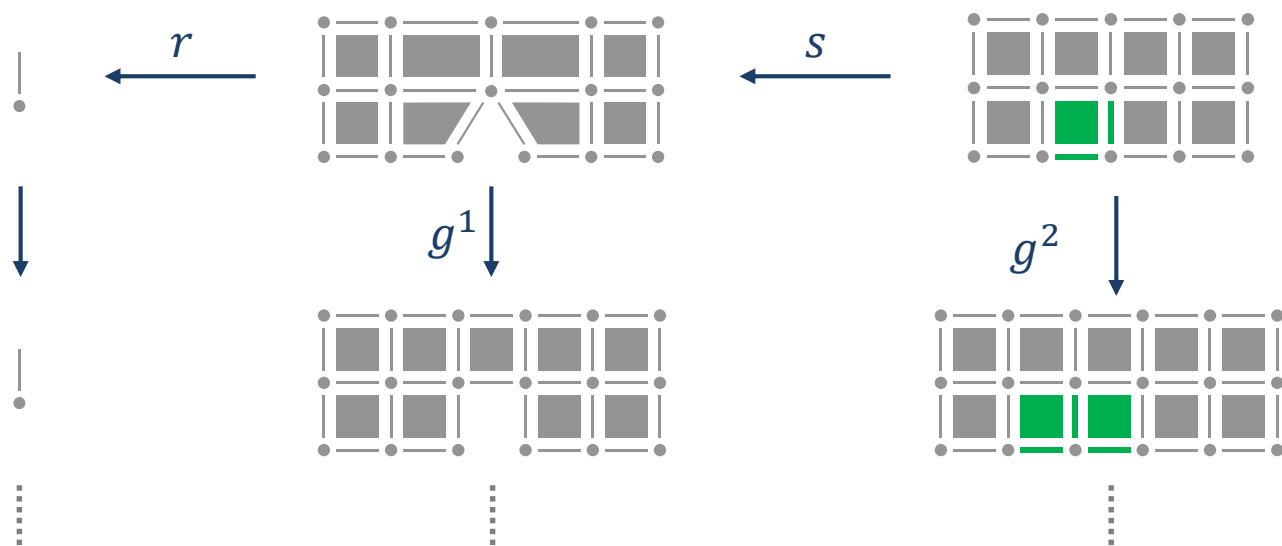
FOCUS ON g COMPLEXITY

$$g^2 = (-s\partial^1 r g^0 \quad s g^1)$$

Possible loss of locality:
 sg^1

- Identity + Variations g^0
- $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with a complexity depending only on A,B,C

- Added complexity
- Initialization complexity



5

REQUIREMENTS

Is the computation complexity only related to the complexity of the operated part?

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Yes, with the following conditions :

- Being able to construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only
- Having a matrix product algorithm using an implicit representation of identity

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Yes, with the following conditions :

- Being able to construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only
- Having a matrix product algorithm using an implicit representation of identity
- Handling sparsity

5

TRIED SOLUTIONS

SOFTWARE	IMPLICIT IDENTITY
EIGEN	
INTELMKL	
NUMPY	
BOOST	

5

TRIED SOLUTIONS

SOFTWARE	IMPLICIT IDENTITY	$\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ BROWSING ONLY A, B, C
EIGEN	Green	Red
INTELMKL		
NUMPY		
BOOST		

Essentially due to sparsity representation schemes

5

TRIED SOLUTIONS

SOFTWARE	IMPLICIT IDENTITY	$\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ BROWSING ONLY A, B, C	SPARSE MATRICES
EIGEN			
INTELMKL			
NUMPY			
BOOST			

5

PROPOSED SOLUTION

Doubly linked matrices + (i, j, v)

$$\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 4 & 0 & 3 & 4 \end{pmatrix}$$

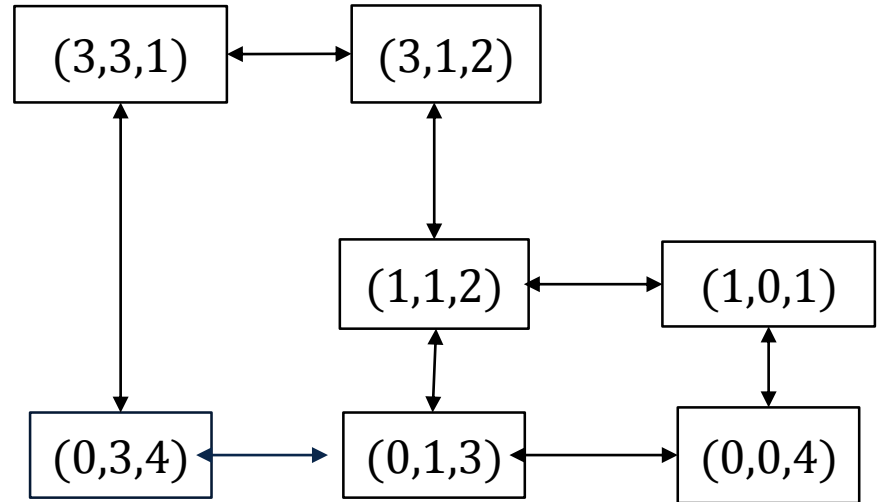
5

PROPOSED SOLUTION

Doubly linked matrices + (i, j, v)

$$\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 4 & 0 & 3 & 4 \end{pmatrix} \begin{matrix} \uparrow \\ i \end{matrix}$$

$\leftarrow j$

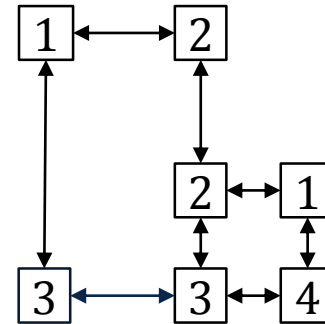


5

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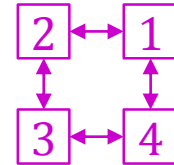
$$\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 4 & 0 & 3 & 4 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$$
$$\begin{pmatrix} 0 & 0 \\ 4 & 0 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 3 & 4 \end{pmatrix}$$

5

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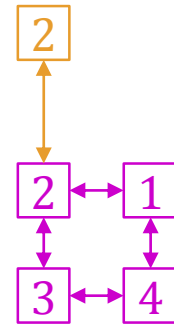


5

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Doubly linked matrices : construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only

$$\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 4 & 0 & 3 & 4 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 2 & 1 \\ 3 & 4 \end{pmatrix}$$

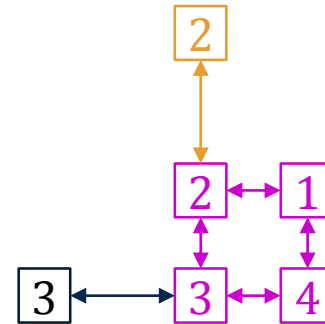


5

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Doubly linked matrices : construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only

$$\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 4 & 0 & 3 & 4 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 2 & 1 \\ 3 & 4 \end{pmatrix}$$

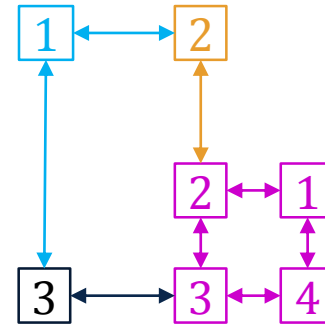


5

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$$\begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 4 & 0 & 3 & 4 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 2 & 1 \\ 3 & 4 \end{pmatrix}$$



5

PROPOSED SOLUTION

Doubly linked matrices : construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only
Implicit representation of identity

$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix}$$

5

PROPOSED SOLUTION

Doubly linked matrices : construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only
Implicit representation of identity

$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

5

PROPOSED SOLUTION

Doubly linked matrices : construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only
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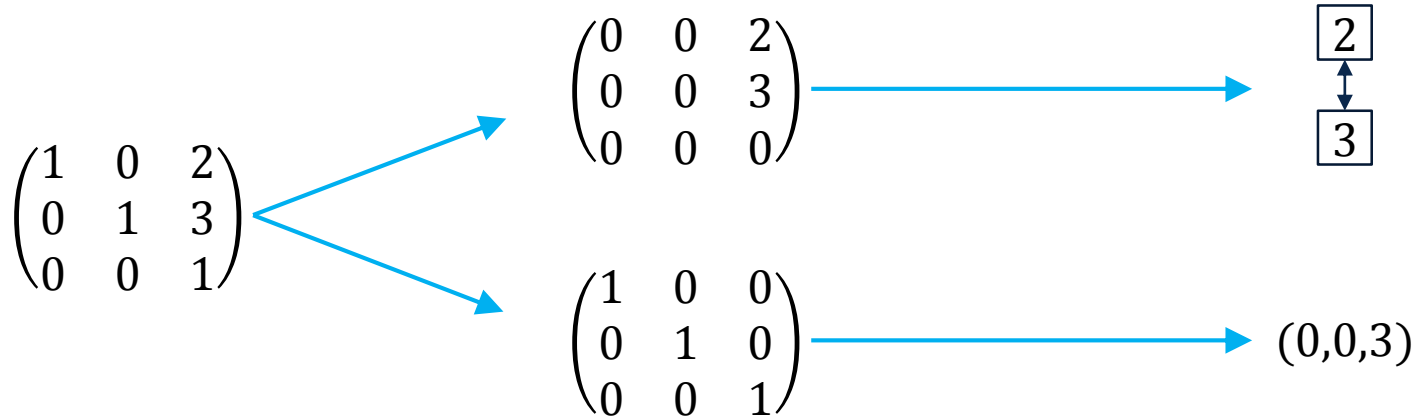
$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow (0,0,3)$$

5

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Implicit representation of identity

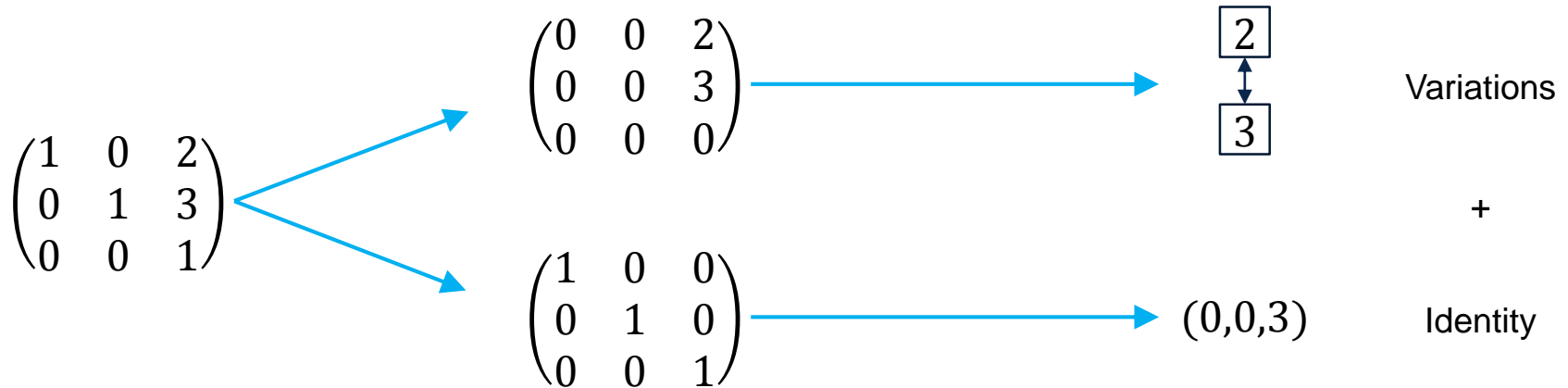


5

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Doubly linked matrices : construct $\begin{pmatrix} A & B \\ C & D \end{pmatrix}$ with an algorithm browsing A, B, C only

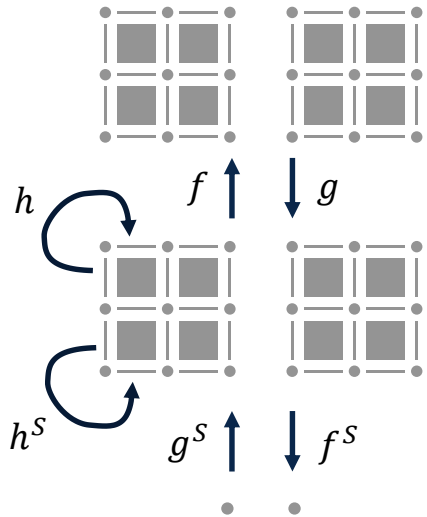
Implicit representation of identity



6: CONCLUSION AND PERSPECTIVES

6

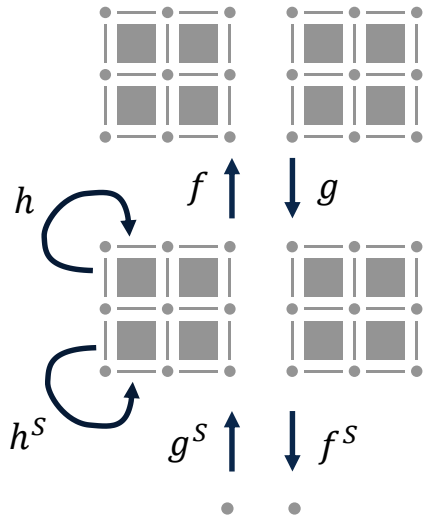
MORE EFFICIENT WITHOUT GENERATORS



6

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Some morphisms can be ignored



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6

CONCLUSION AND PERSPECTIVES

At each step: control of the object construction according to computed information

- Short exact sequence based method => tracking homology variations

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CONCLUSION AND PERSPECTIVES

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Perspectives

- Apply the method to the inverse operation (splitting cells)

6

CONCLUSION AND PERSPECTIVES

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- Theoretical and experimental study => complexity depending on the operated part
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Perspectives

- Apply the method to the inverse operation (splitting cells)
- Apply in an application case: animation
- Parallelization

GARBAGE

7

ATTACHMENTS

Sparse matrices representation schemes

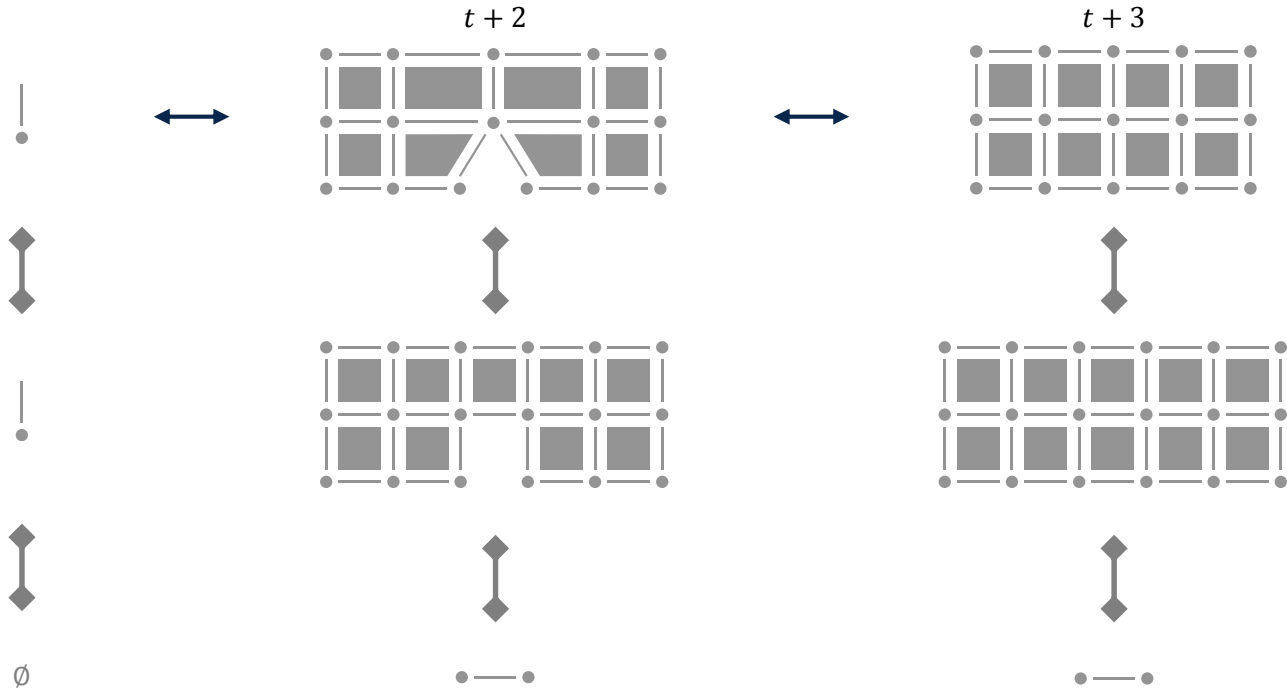
$$\begin{pmatrix} 0 & 4 & 1 \\ 2 & 0 & 5 \\ 0 & 3 & 0 \end{pmatrix}$$

CCS :

VALUES	2	4	3	1	5
ROW INDEX	1	0	2	0	1
COLUMN START INDEX	0	1	3	6	

5

ANALYSIS : SPATIAL COMPLEXITY EVOLUTION ON COMPLEXES



- Operation
- Added part
- Initialization

∅

5

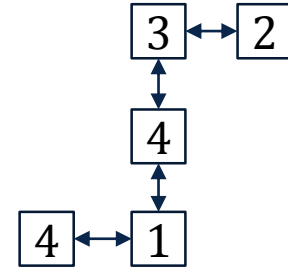
PROPOSED SOLUTION

Implicit identity

$$\begin{pmatrix} 1 & 3 & 2 \\ 0 & 5 & 0 \\ 4 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 3 & 2 \\ 0 & 4 & 0 \\ 4 & 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$



(0,0,2)

□ Identity block

