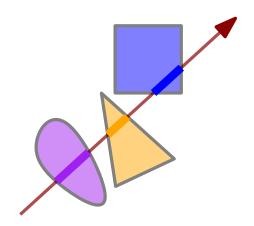
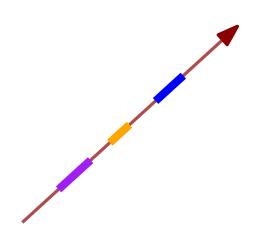
Forbidden Patterns in Geometric Permutations by Combinatorial Lifting

Xavier Goaoc, Andreas Holmsen, Cyril Nicaud

oriented line that intersects every set  $\rightarrow$  **permutation** (or ordering) of the sets

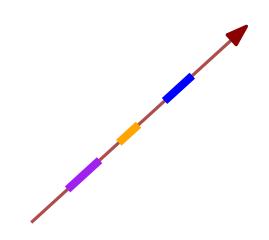


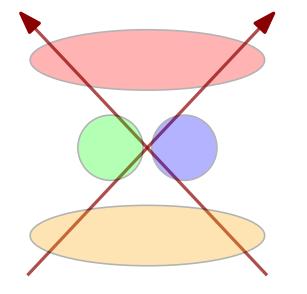
oriented line that intersects every set  $\rightarrow$  **permutation** (or ordering) of the sets



oriented line that intersects every set  $\rightarrow$  **permutation** (or ordering) of the sets

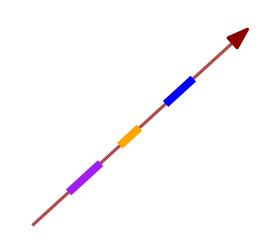
What is the **maximum number**  $g_d(n)$  of permutations realizable on n sets in  $\mathbb{R}^d$ ?

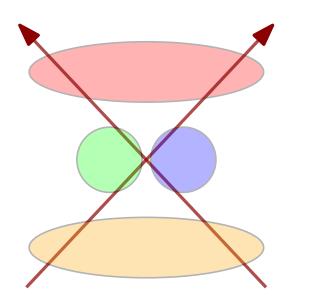




oriented line that intersects every set  $\rightarrow$  **permutation** (or ordering) of the sets

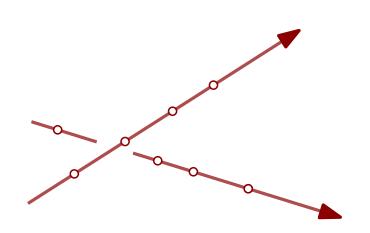
What is the **maximum number**  $g_d(n)$  of permutations realizable on n sets in  $\mathbb{R}^d$ ?

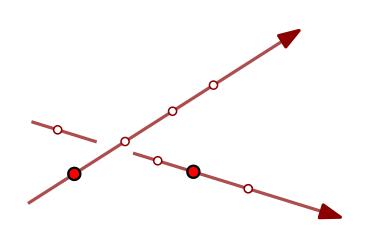


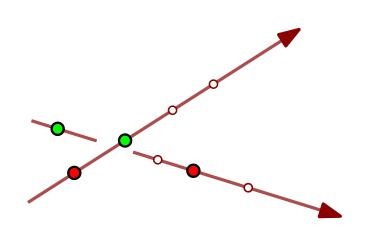


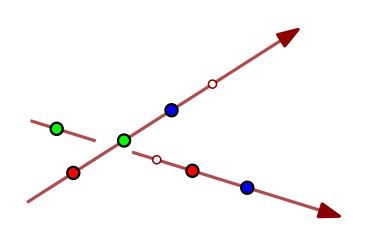
 $g_{2}(n) = 2n - 2 \ [1992]$   $g_{d}(n) = O \left(n^{2d-2}\right) \ [1992]$   $g_{d}(n) = \Omega \left(n^{d-1}\right) \ [2002]$   $g_{d}(n) = O \left(n^{2d-3} \log n\right) \ [2010]$ 

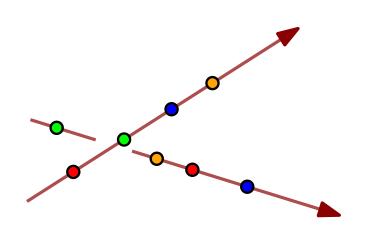
special cases are understood: balls, fatness, ...

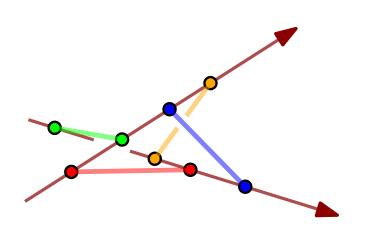


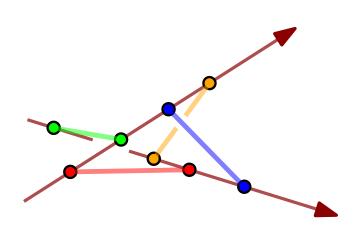








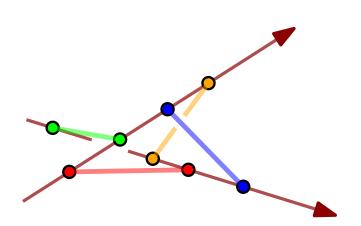




Simplest non-trivial constraints

We design an algorithm deciding this.

Implementation (  $\sim$  600 lines of python)



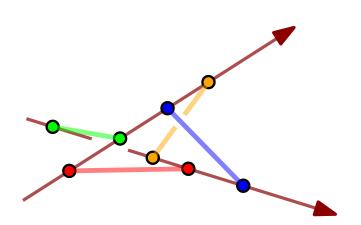
Simplest non-trivial constraints

We design an algorithm deciding this.

Implementation ( $\sim$  600 lines of python)

Experimental results:

**Theorem.** Every triple of permutations on  $n \leq 5$  elements is geometrically realizable in  $\mathbb{R}^3$ .



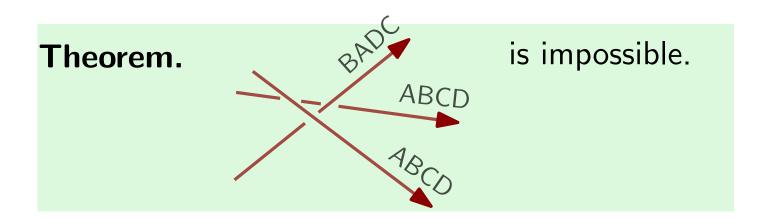
Simplest non-trivial constraints

We design an algorithm deciding this.

Implementation ( $\sim$  600 lines of python)

Experimental results:

**Theorem.** Every triple of permutations on  $n \leq 5$  elements is geometrically realizable in  $\mathbb{R}^3$ .



## The computational problem

 $GEOMETRIC\_REALISABILITY\_3D$ 

Input: Three orders on  $\{1, 2, \ldots, n\}$ 

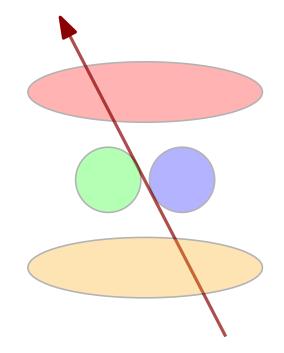
Output: Whether there exists n disjoint compact convex sets in  $\mathbb{R}^3$  and three lines intersecting them in these orders.

# From geometry to algebra

GEOMETRIC NORMALIZATION

Start with 3 lines and n disjoint compact convex sets realizing 3 given orders.

We can assume that the lines are **pairwise skew**.

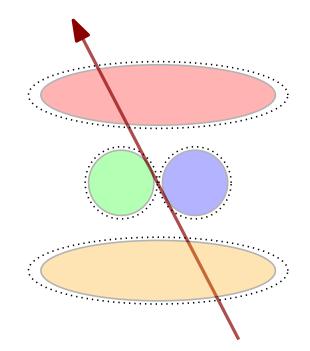


### GEOMETRIC NORMALIZATION

Start with 3 lines and n disjoint compact convex sets realizing 3 given orders.

We can assume that the lines are **pairwise skew**.

Compactness  $\Rightarrow$  we can thicken the sets  $\Rightarrow$  we can perturb the lines

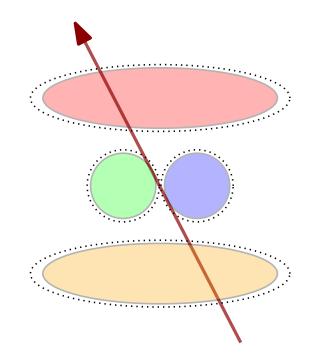


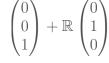
### GEOMETRIC NORMALIZATION

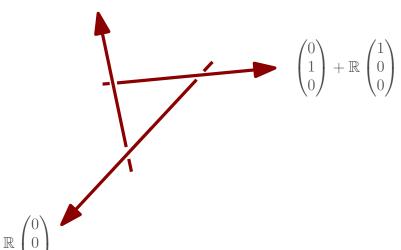
Start with 3 lines and n disjoint compact convex sets realizing 3 given orders.

We can assume that the lines are **pairwise skew**.

Compactness  $\Rightarrow$  we can thicken the sets  $\Rightarrow$  we can perturb the lines

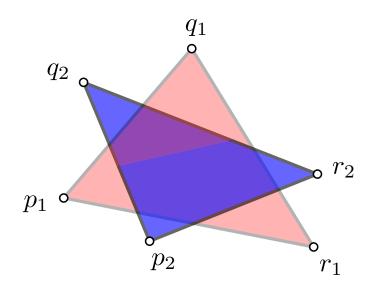




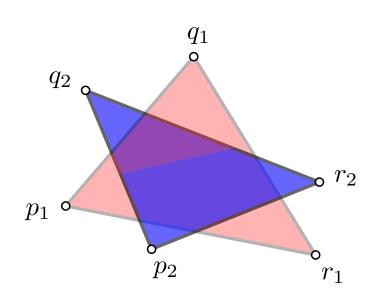


We can crop the sets to **triangles** with vertices **on the lines**.

We can **choose** the lines (up to reversing some permutations).



$$[p, q, r, s] \stackrel{\text{def}}{=} \operatorname{sign} \begin{vmatrix} x_p & x_q & x_r & x_s \\ y_p & y_q & y_r & y_s \\ z_p & z_q & z_r & z_s \\ 1 & 1 & 1 & 1 \end{vmatrix}$$

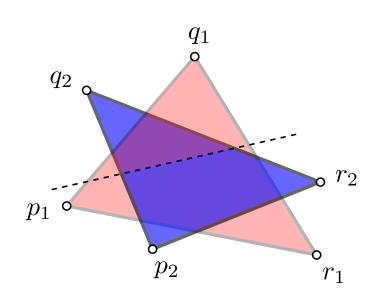


(1) does the plane of a triangle separate the vertices of the other?

$[p_1, q_1, r_1, p_2]$	$[p_2, a]$
$[p_1, q_1, r_1, q_2]$	$[p_2, 0]$
$[p_1, q_1, r_1, r_2]$	$[p_2, c_2]$

 $p_2, q_2, r_2, p_1] \ p_2, q_2, r_2, q_1] \ p_2, q_2, r_2, r_1]$ 

$$[p, q, r, s] \stackrel{\text{def}}{=} \operatorname{sign} \begin{vmatrix} x_p & x_q & x_r & x_s \\ y_p & y_q & y_r & y_s \\ z_p & z_q & z_r & z_s \\ 1 & 1 & 1 & 1 \end{vmatrix}$$



$$[p, q, r, s] \stackrel{\text{def}}{=} \operatorname{sign} \begin{vmatrix} x_p & x_q & x_r & x_s \\ y_p & y_q & y_r & y_s \\ z_p & z_q & z_r & z_s \\ 1 & 1 & 1 & 1 \end{vmatrix}$$

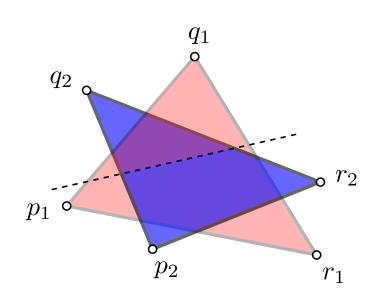
(1) does the plane of a triangle separate the vertices of the other?

$[p_1, q_1, r_1, p_2]$	$[p_2, q_2, r_2, p_1]$
$[p_1, q_1, r_1, q_2]$	$\left[ p_{2},q_{2},r_{2},q_{1} ight]$
$[p_1, q_1, r_1, r_2]$	$[p_2, q_2, r_2, r_1]$

(2) if not, each triangle meets the intersection of the two planes.Do the two segments intersect?

rename p, q, r into a, b, c so that a is separated from  $\{b, c\}$ 

$$[a_1, b_1, a_2, b_2] = +1$$
 or  $[a_1, c_1, c_2, a_2] = +1$ 



$$[p, q, r, s] \stackrel{\text{def}}{=} \operatorname{sign} \begin{vmatrix} x_p & x_q & x_r & x_s \\ y_p & y_q & y_r & y_s \\ z_p & z_q & z_r & z_s \\ 1 & 1 & 1 & 1 \end{vmatrix}$$

(1) does the plane of a triangle separate the vertices of the other?

$[p_1, q_1, r_1, p_2]$	$[p_2, q_2, r_2, p_1]$
$[p_1, q_1, r_1, q_2]$	$\left[ p_{2},q_{2},r_{2},q_{1} ight]$
$[p_1, q_1, r_1, r_2]$	$[p_2, q_2, r_2, r_1]$

(2) if not, each triangle meets the intersection of the two planes.Do the two segments intersect?

rename p, q, r into a, b, c so that a is separated from  $\{b, c\}$ 

$$[a_1, b_1, a_2, b_2] = +1$$
 or  $[a_1, c_1, c_2, a_2] = +1$ 

SEMI-ALGEBRAIC FORMULATION

Parameterize candidate realizations by 
$$\mathbb{R}^{3n}$$
  
*i*th triangle = convex hull of  $\begin{pmatrix} x_i \\ 1 \\ 0 \end{pmatrix}$ ,  $\begin{pmatrix} 0 \\ y_i \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ 0 \\ z_i \end{pmatrix}$ .

G-D algorithm  $\leftrightarrow$  polynomial decision tree

Orientation predicates are polynomials in the parameters.

The realizations form a semi-algebraic set S defined by  $\Theta\left(n^2\right)$  inequations.

SEMI-ALGEBRAIC FORMULATION

Parameterize candidate realizations by 
$$\mathbb{R}^{3n}$$
  
*i*th triangle = convex hull of  $\begin{pmatrix} x_i \\ 1 \\ 0 \end{pmatrix}$ ,  $\begin{pmatrix} 0 \\ y_i \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 1 \\ 0 \\ z_i \end{pmatrix}$ .

G-D algorithm  $\leftrightarrow$  polynomial decision tree

Orientation predicates are polynomials in the parameters.

The realizations form a semi-algebraic set S defined by  $\Theta\left(n^{2}\right)$  inequations.

TESTING EMPTINESS OF A SEMI-ALGEBRAIC SET

CAD, critical points method, ...

 $(\text{number of polynomials} \times \text{maximum degree})^{O(\text{number of variables})}$ 

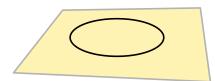
# From algebra to combinatorics

A trick to **linearize** problems on polynomials of degree  $\leq k$  in  $\mathbb{R}^d$ 

$$(x_1, x_2, \dots, x_d) \in \mathbb{R}^d \\ \mapsto \begin{array}{c} (x_1, x_2, \dots, x_d, x_1^2, x_1 x_2, \\ x_1 x_3, \dots, x_d^2, x_1^3, \dots, x_d^k) \end{array} \in \mathbb{R}^{\binom{d+k}{d}}$$

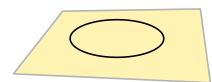
A trick to **linearize** problems on polynomials of degree  $\leq k$  in  $\mathbb{R}^d$ 

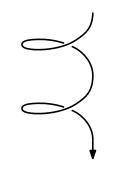
$$(x_1, x_2, \dots, x_d) \in \mathbb{R}^d \\ \mapsto \begin{array}{c} (x_1, x_2, \dots, x_d, x_1^2, x_1 x_2, \\ x_1 x_3, \dots, x_d^2, x_1^3, \dots, x_d^k) \end{array} \in \mathbb{R}^{\binom{d+k}{d}}$$



**Theorem.** Any d finite measures in  $\mathbb{R}^d$  can be simultaneously bisected by a hyperplane. A trick to **linearize** problems on polynomials of degree  $\leq k$  in  $\mathbb{R}^d$ 

$$(x_1, x_2, \dots, x_d) \in \mathbb{R}^d \\ \mapsto \begin{array}{c} (x_1, x_2, \dots, x_d, x_1^2, x_1 x_2, \\ x_1 x_3, \dots, x_d^2, x_1^3, \dots, x_d^k) \end{array} \in \mathbb{R}^{\binom{d+k}{d}}$$





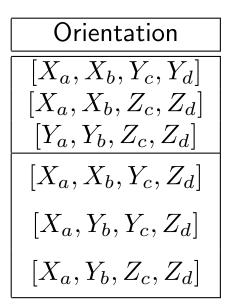
 $\mathcal{M}_2 \subset \mathbb{R}^6$ 

**Theorem.** Any d finite measures in  $\mathbb{R}^d$  can be simultaneously bisected by a hyperplane.

**Theorem.** Any  $\binom{d+k}{d}$  finite measures in  $\mathbb{R}^d$  can be simultaneously bisected by the zero set of a polynomial of degree k.

### Factorizing the $\bigtriangleup\bigtriangleup$ predicates

Т



### Factorizing the $\triangle \triangle$ predicates

1

Orientation	Determinant
$\boxed{[X_a, X_b, Y_c, Y_d]}$	$(x_a - x_b)(y_c - y_d)$
$\left[X_a, X_b, Z_c, Z_d\right]$	$(x_a - x_b)(z_c - z_d)$
$[Y_a, Y_b, Z_c, Z_d]$	$(y_a - y_b)(z_c - z_d)$
$[X_a, X_b, Y_c, Z_d]$	$(x_a - x_b)(y_c z_d - z_d + 1)$
$[X_a, Y_b, Y_c, Z_d]$	$(y_b - y_c)(x_a - x_a z_d - 1)$
$[X_a, Y_b, Z_c, Z_d]$	$(z_c - z_d)(x_a y_b + 1 - y_b)$

### Factorizing the $\bigtriangleup\bigtriangleup$ predicates

$$X_{i} = \begin{pmatrix} x_{i} \\ 1 \\ 0 \end{pmatrix}, Y_{i} = \begin{pmatrix} 0 \\ y_{i} \\ 1 \end{pmatrix} \text{ and } Z_{i} = \begin{pmatrix} 1 \\ 0 \\ z_{i} \end{pmatrix} \qquad [p,q,r,s] = \text{sign} \begin{vmatrix} x_{p} & x_{q} & x_{r} & x_{s} \\ y_{p} & y_{q} & y_{r} & y_{s} \\ z_{p} & z_{q} & z_{r} & z_{s} \\ 1 & 1 & 1 & 1 \end{vmatrix}$$

Orientation	Determinant	Decomposition
$\boxed{[X_a, X_b, Y_c, Y_d]}$	$(x_a - x_b)(y_c - y_d)$	$(x_a - x_b)(y_c - y_d)$
$\left[X_a, X_b, Z_c, Z_d\right]$	$(x_a - x_b)(z_c - z_d)$	$(x_a - x_b)(z_c - z_d)$
$\left[Y_a, Y_b, Z_c, Z_d\right]$	$(y_a - y_b)(z_c - z_d)$	$(y_a - y_b)(z_c - z_d)$
$\left[X_a, X_b, Y_c, Z_d\right]$	$(x_a - x_b)(y_c z_d - z_d + 1)$	$(x_a - x_b)(y_c - 1)\left(z_d - \frac{1}{1 - y_c}\right)$
$\left[X_a, Y_b, Y_c, Z_d\right]$	$(y_b - y_c)(x_a - x_a z_d - 1)$	$-(y_b - y_c)(z_d - 1)\left(x_a - \frac{1}{1 - z_d}\right)$
$\left[X_a, Y_b, Z_c, Z_d\right]$	$(z_c - z_d)(x_a y_b + 1 - y_b)$	$(z_c - z_d)(x_a - 1)\left(y_b - \frac{1}{1 - x_a}\right)$

### Factorizing the $\bigtriangleup\bigtriangleup$ predicates

$$X_{i} = \begin{pmatrix} x_{i} \\ 1 \\ 0 \end{pmatrix}, Y_{i} = \begin{pmatrix} 0 \\ y_{i} \\ 1 \end{pmatrix} \text{ and } Z_{i} = \begin{pmatrix} 1 \\ 0 \\ z_{i} \end{pmatrix} \qquad [p,q,r,s] = \text{sign} \begin{vmatrix} x_{p} & x_{q} & x_{r} & x_{s} \\ y_{p} & y_{q} & y_{r} & y_{s} \\ z_{p} & z_{q} & z_{r} & z_{s} \\ 1 & 1 & 1 & 1 \end{vmatrix}$$

Orientation	Determinant	Decomposition
$\begin{bmatrix} X_a, X_b, Y_c, Y_d \end{bmatrix}$	$(x_a - x_b)(y_c - y_d)$	$(x_a - x_b)(y_c - y_d)$
$\left[X_a, X_b, Z_c, Z_d\right]$	$(x_a - x_b)(z_c - z_d)$	$(x_a - x_b)(z_c - z_d)$
$\left[Y_a, Y_b, Z_c, Z_d\right]$	$(y_a - y_b)(z_c - z_d)$	$(y_a - y_b)(z_c - z_d)$
$\left[X_a, X_b, Y_c, Z_d\right]$	$(x_a - x_b)(y_c z_d - z_d + 1)$	$\left  (x_a - x_b)(y_c - 1)\left(z_d - \frac{1}{1 - y_c}\right) \right $
$\left[X_a, Y_b, Y_c, Z_d\right]$	$\left( (y_b - y_c)(x_a - x_a z_d - 1) \right)$	$-(y_b - y_c)(z_d - 1)\left(x_a - \frac{1}{1 - z_d}\right)$
$\left[X_a, Y_b, Z_c, Z_d\right]$	$(z_c - z_d)(x_a y_b + 1 - y_b)$	$\left(z_c - z_d)(x_a - 1)\left(y_b - \frac{1}{1 - x_a}\right)\right)$

 $f(t) \stackrel{\text{\tiny def}}{=} \frac{1}{1-t}$ 

The order on  $\{x_1, f(x_1), x_2, f(x_2), \dots, z_n, f(z_n), \mathbf{1}\}$  determines all orientations.

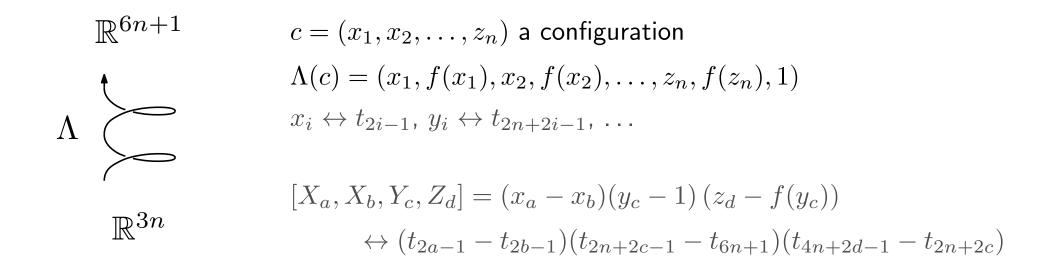
## COMBINATORIAL LIFTING

$$c = (x_1, x_2, \dots, z_n) \text{ a configuration}$$
$$\Lambda(c) = (x_1, f(x_1), x_2, f(x_2), \dots, z_n, f(z_n), 1)$$
$$x_i \leftrightarrow t_{2i-1}, y_i \leftrightarrow t_{2n+2i-1}, \dots$$

$$[X_a, X_b, Y_c, Z_d] = (x_a - x_b)(y_c - 1) (z_d - f(y_c))$$
  

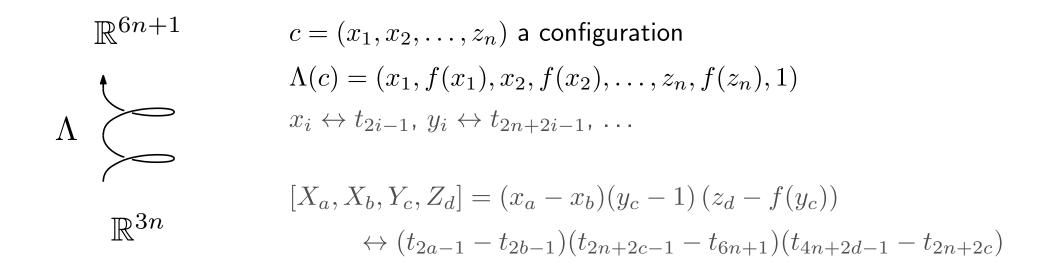
$$\leftrightarrow (t_{2a-1} - t_{2b-1})(t_{2n+2c-1} - t_{6n+1})(t_{4n+2d-1} - t_{2n+2c})$$

### COMBINATORIAL LIFTING



Find an order on  $(t_1, t_2, \ldots, t_{6n+1})$  that **satisfies** the symbolic lifting of the boolean formula defining S and is **realizable** by some  $\Lambda(c)$ .

#### COMBINATORIAL LIFTING



Find an order on  $(t_1, t_2, \ldots, t_{6n+1})$  that **satisfies** the symbolic lifting of the boolean formula defining S and is **realizable** by some  $\Lambda(c)$ .

The **realizability problem** becomes easy if we lift to  $(x_1, f(x_1), f^{(2)}(x_1), x_2, \dots, f^{(2)}(z_n), 0, 1)$  Combinatorial lifting

Remember: 
$$f(t) \stackrel{\text{\tiny def}}{=} \frac{1}{1-t}$$

f has nice properties:

1. 
$$f^{(3)} = f \circ f \circ f = id$$

- 2. f permutes circularly  $(-\infty, 0)$ , (0, 1) and  $(1, +\infty)$
- 3. f is increasing on each of these intervals

COMBINATORIAL LIFTING

Remember: 
$$f(t) \stackrel{\text{\tiny def}}{=} \frac{1}{1-t}$$

### f has nice properties:

1. 
$$f^{(3)} = f \circ f \circ f = id$$

- 2. f permutes circularly  $(-\infty, 0)$ , (0, 1) and  $(1, +\infty)$
- 3. f is increasing on each of these intervals

**Theorem.** An order in  $S_{3n+2}$  can be realized by  $\{x_1, f(x_1), f^{(2)}(x_1), x_2, f(x_2), f^{(2)}(x_2), \dots, z_n, f(z_n), f^{(2)}(z_n), 0, 1\}$  iff it is compatible with properties 1-2-3.

COMBINATORIAL LIFTING

Remember: 
$$f(t) \stackrel{\text{\tiny def}}{=} \frac{1}{1-t}$$

#### f has nice properties:

1. 
$$f^{(3)} = f \circ f \circ f = id$$

- 2. f permutes circularly  $(-\infty, 0)$ , (0, 1) and  $(1, +\infty)$
- 3. f is increasing on each of these intervals

**Theorem.** An order in  $S_{3n+2}$  can be realized by  $\{x_1, f(x_1), f^{(2)}(x_1), x_2, f(x_2), f^{(2)}(x_2), \dots, z_n, f(z_n), f^{(2)}(z_n), 0, 1\}$  iff it is compatible with properties 1-2-3.

"the action of f"

### Solving the combinatorial problem

 $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ , each family ordered by an input permutation

 $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ , each family ordered by an input permutation

Add 6n symbolic variables.

•<sub>*i*,*j*</sub> which represents  $f^{(j)}(\bullet_i)$ , for j = 1, 2 and  $\bullet \in \{x, y, z\}$ .

 $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ , each family ordered by an input permutation

Add 6n symbolic variables.

•<sub>*i*,*j*</sub> which represents  $f^{(j)}(\bullet_i)$ , for j = 1, 2 and  $\bullet \in \{x, y, z\}$ .

Insert 0, 1 in each ordered family  $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ . brute force:  $\Theta(n^6)$  cases.

 $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ , each family ordered by an input permutation

Add 6n symbolic variables.

•<sub>*i*,*j*</sub> which represents  $f^{(j)}(\bullet_i)$ , for j = 1, 2 and  $\bullet \in \{x, y, z\}$ .

Insert 0,1 in each ordered family  $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ . brute force:  $\Theta(n^6)$  cases.

Order each family  $\{\bullet_{i,j}\}_i$  to be compatible with the action of f.

 $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ , each family ordered by an input permutation

Add 6n symbolic variables.

•<sub>*i*,*j*</sub> which represents  $f^{(j)}(\bullet_i)$ , for j = 1, 2 and  $\bullet \in \{x, y, z\}$ .

Insert 0, 1 in each ordered family  $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ . brute force:  $\Theta(n^6)$  cases.

Order each family  $\{\bullet_{i,j}\}_i$  to be compatible with the action of f.

A partial order  $\mathcal{P}_0$  whose linear extensions contain all solution orders

 $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ , each family ordered by an input permutation

Add 6n symbolic variables.

•<sub>*i*,*j*</sub> which represents  $f^{(j)}(\bullet_i)$ , for j = 1, 2 and  $\bullet \in \{x, y, z\}$ .

Insert 0, 1 in each ordered family  $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ . brute force:  $\Theta(n^6)$  cases.

Order each family  $\{\bullet_{i,j}\}_i$  to be compatible with the action of f.

A partial order  $\mathcal{P}_0$  whose linear extensions contain all solution orders

We then refine  $\mathcal{P}$  into  $\mathcal{P}_1, \mathcal{P}_2, \ldots$  such that for each  $\mathcal{P}_i$ , all or none linear extension is a solution order.

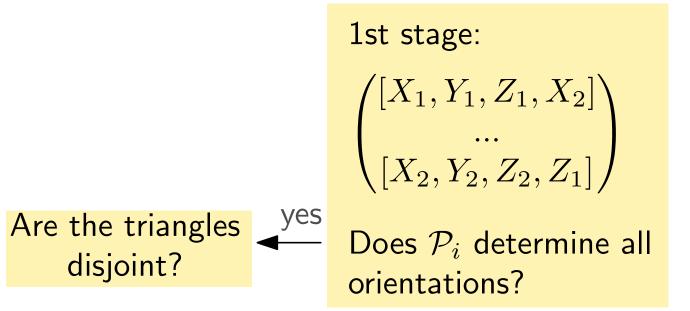
Refine/split  $\mathcal{P}_i$  one pair of triangle at a time:

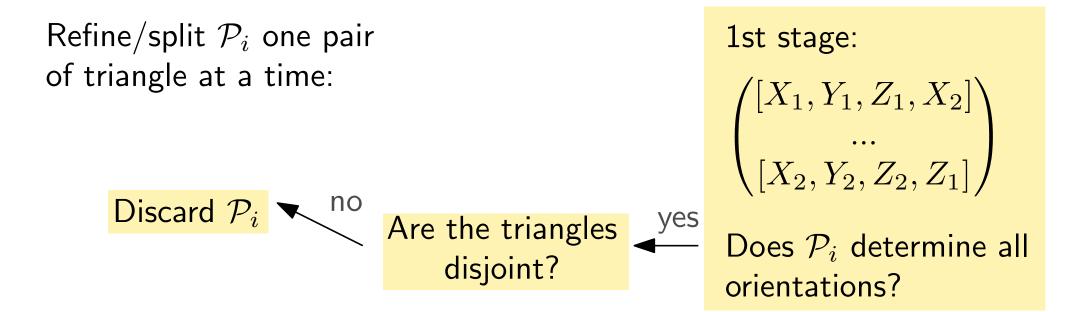
1st stage:  $\begin{pmatrix} [X_1, Y_1, Z_1, X_2] \\ \dots \\ [X_2, Y_2, Z_2, Z_1] \end{pmatrix}$  Refine/split  $\mathcal{P}_i$  one pair of triangle at a time:

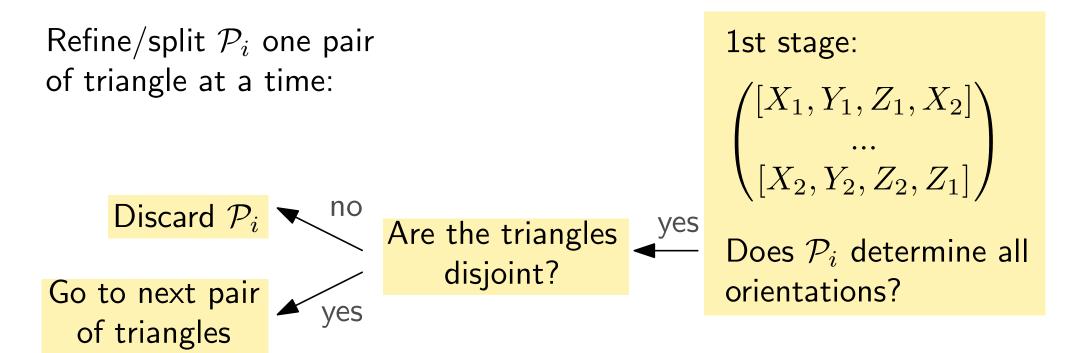
1st stage:  $\begin{pmatrix} [X_1, Y_1, Z_1, X_2] \\ ... \\ [X_2, Y_2, Z_2, Z_1] \end{pmatrix}$ 

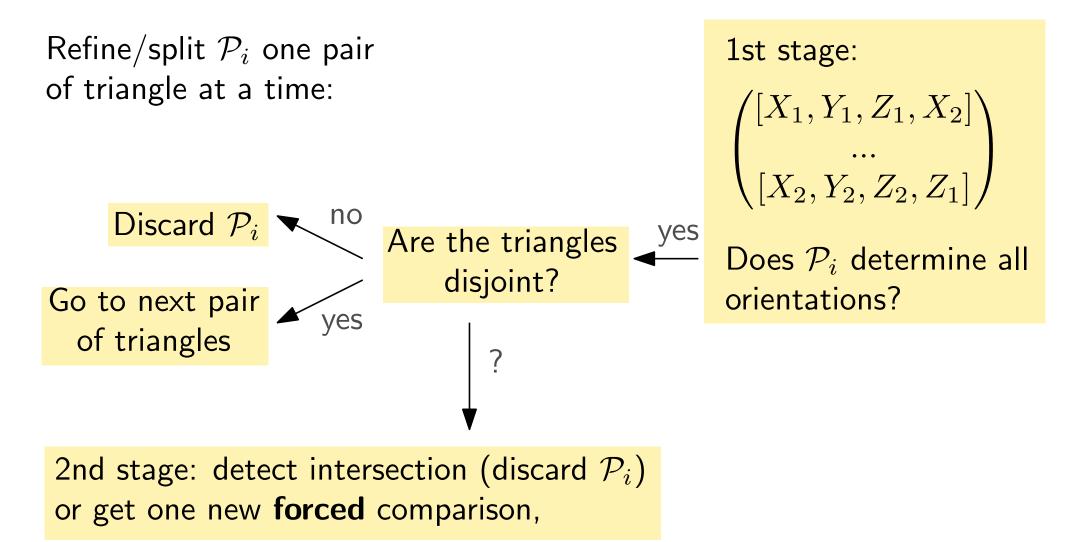
Does  $\mathcal{P}_i$  determine all orientations?

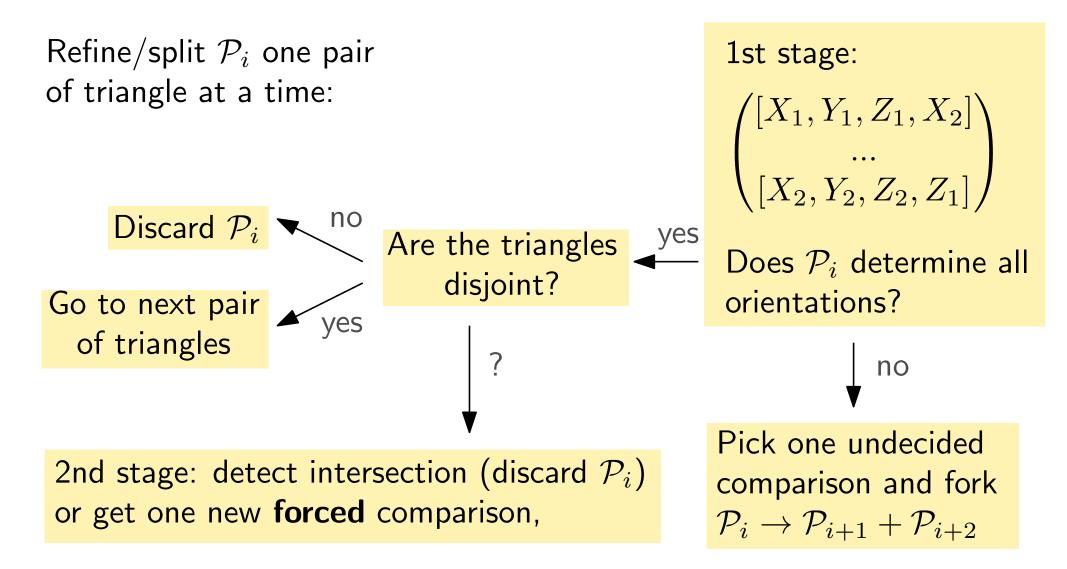
Refine/split  $\mathcal{P}_i$  one pair of triangle at a time:

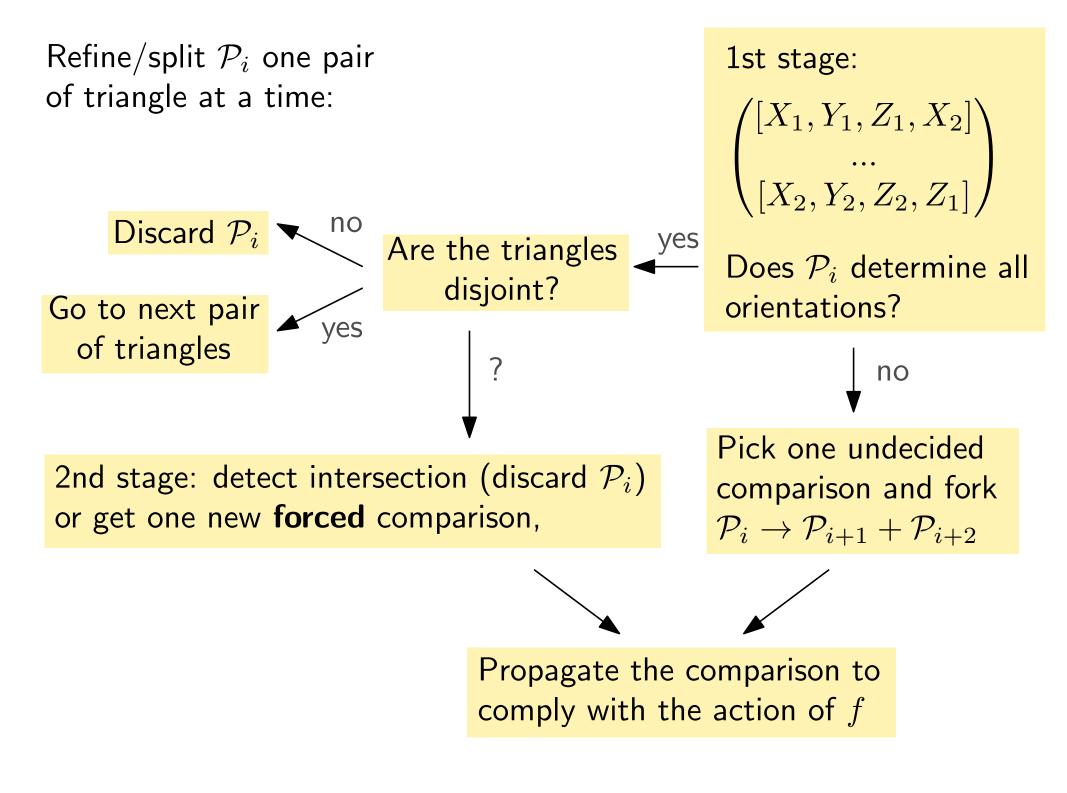




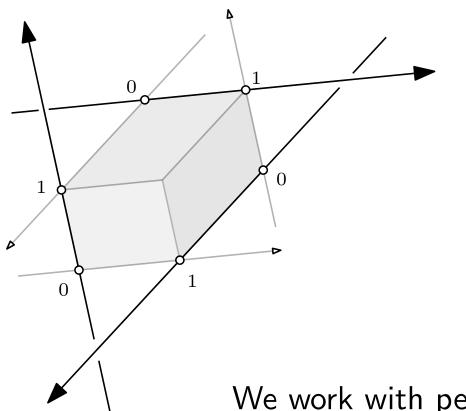








## Using the implementation



"Insert 0, 1 in each ordered family  $\{x_i\}$ ,  $\{y_i\}$ ,  $\{z_i\}$ "

has a geometric meaning...

We work with permutations **tagged** with 0 and 1.

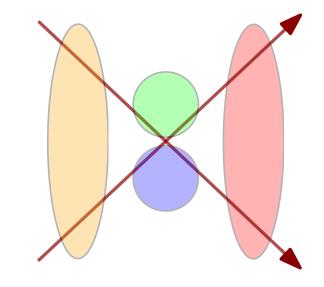
# We compute the **minimally forbidden** triples of tagged permutations of size 2 to 6.

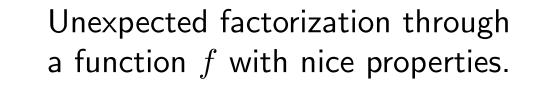
Size 2: equivalent to a lemma of [Asinowski-Katchalski 2005] Size 5 and 6: none

### To summarize

A "hard nut" in discrete geometry.

Standard reduction to a the emptiness of a semi-algebraic set.





### Allows to test emptiness combinatorially.

New geometric results

 $\mathbb{R}^{9n+2}$ 

 $\mathbb{R}^{3n}$ 

+ reveals some useful structure

